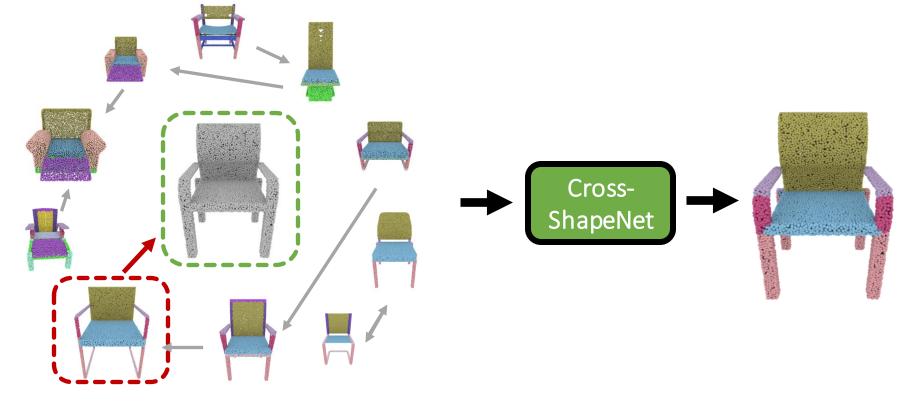
# Cross-Shape Attention for Part Segmentation of 3D Point Clouds



Marios Loizou<sup>†1</sup>Siddhant Garg<sup>†2</sup>Dmitry Petrov<sup>†2</sup>Melinos Averkiou<sup>1</sup>Evangelos Kalogerakis<sup>2</sup>

<sup>1</sup>University of Cyprus / CYENS CoE

<sup>2</sup>University of Massachusetts Amherst

**†** Equal Contribution

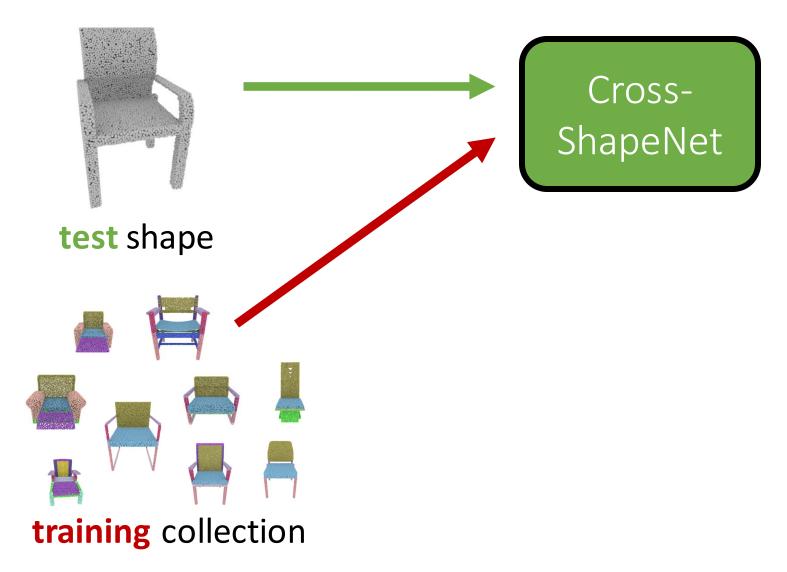


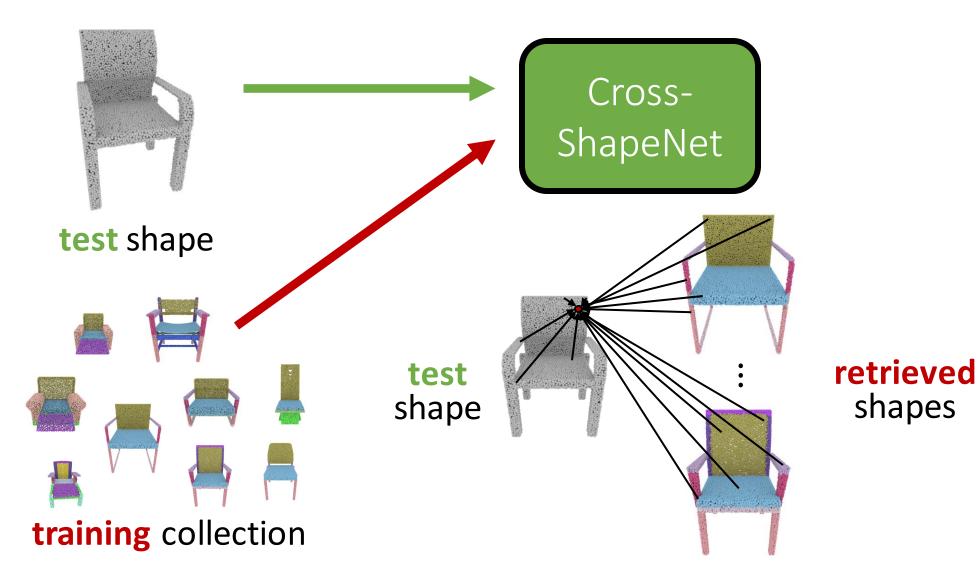
test shape

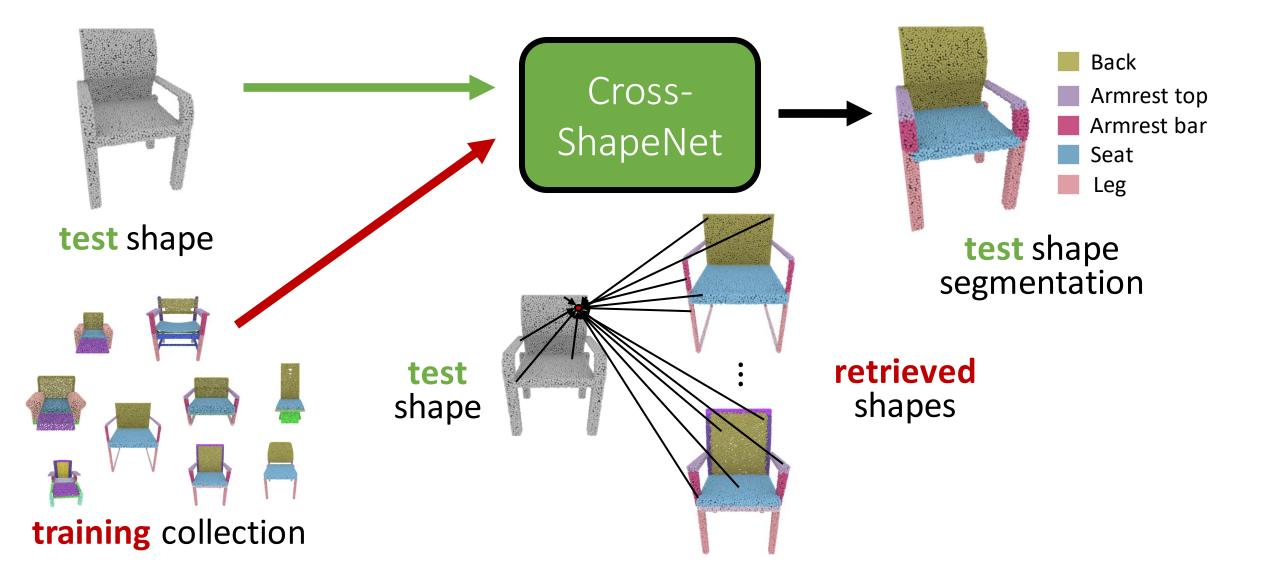


test shape

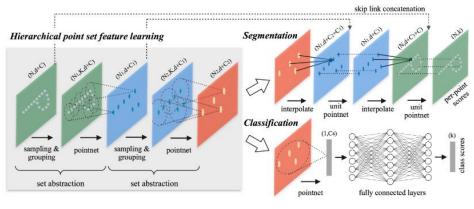






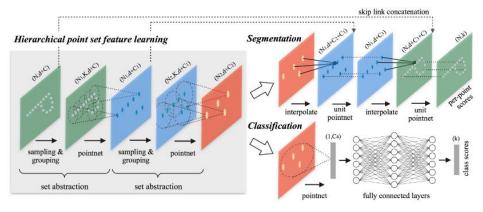


#### **Prior work**: Point-based networks

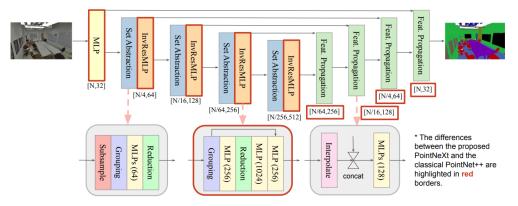


PointNet++ [Qi et al. 2017]

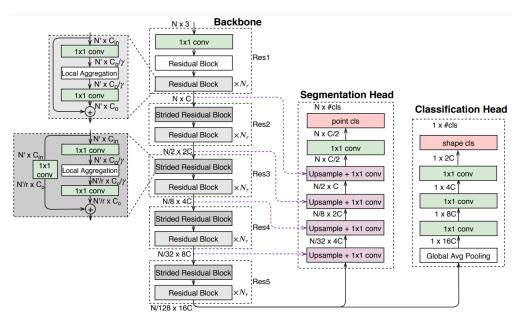
#### Prior work: Point-based networks



PointNet++ [Qi et al. 2017]



PointNeXt [Qian et al. 2022]



CloserLook3D [Liu et al. 2020]

#### **Prior work**: GCNs for non-Eucledian data

Input •

ResGCN k=16 f=64 d=1

ResGCN

k=16 f=64 d=1

-

ResGCN k=16 f=64 d=2

ResGCN k=16 f=64 d=26

ResGCN k=16 f=64 d=27

ResGCN

Backbone

Input 🛉

DenseGCN k=16 f=64 d=1

DenseGCN

k=16 f=32 d=1

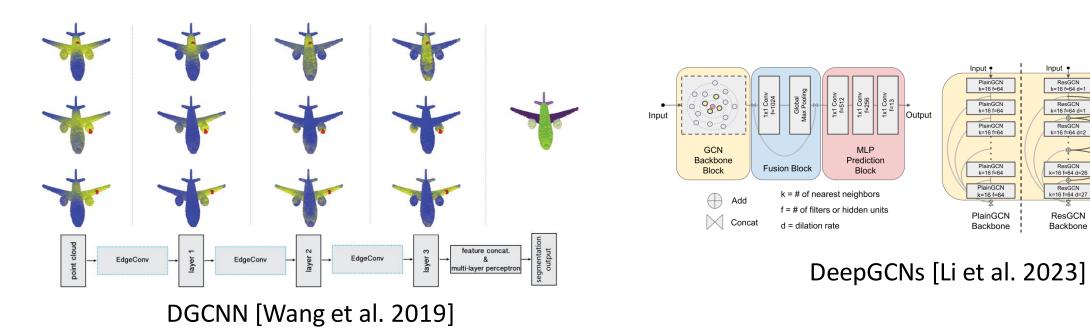
DenseGCN k=16 f=32 d=2

DenseGCN k=16 f=32 d=26

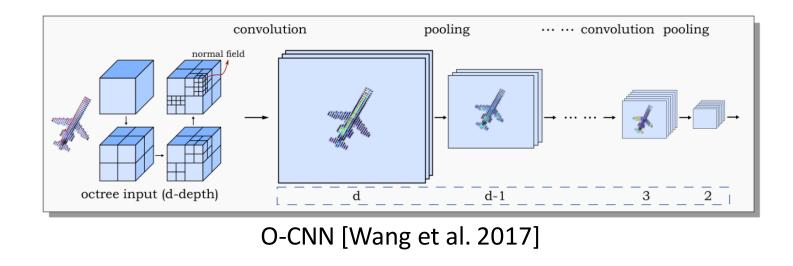
DenseGCN k=16 f=32 d=27

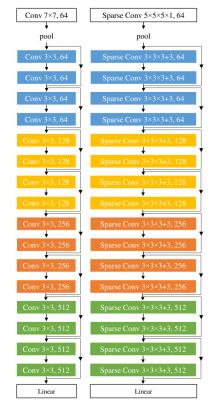
DenseGCN

Backbone



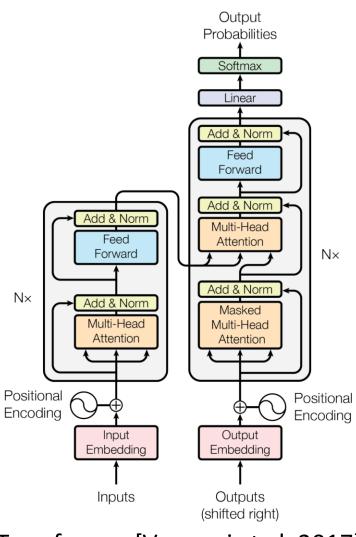
### Prior work: Volumetric networks

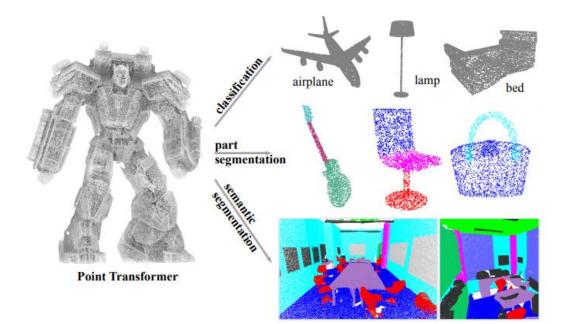




#### MinkowskiNet [Choy et al. 2019]

## Prior work: Attention is All You Need

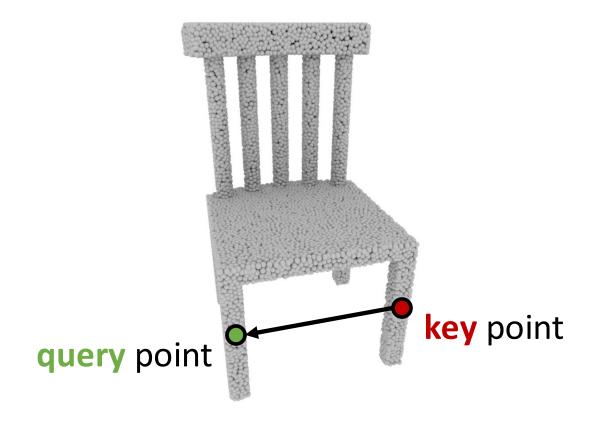


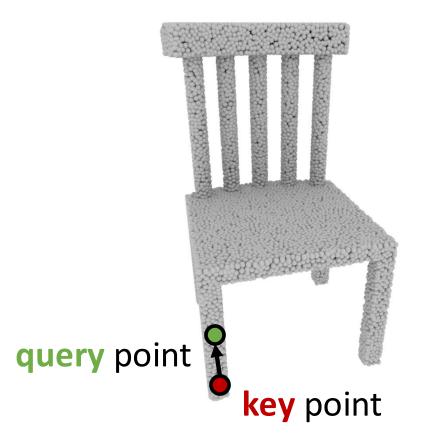


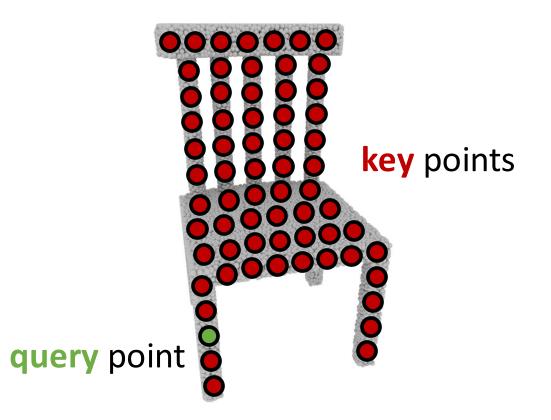
PointTransformer v1/v2 [Zhao et al. 2021, 2022]

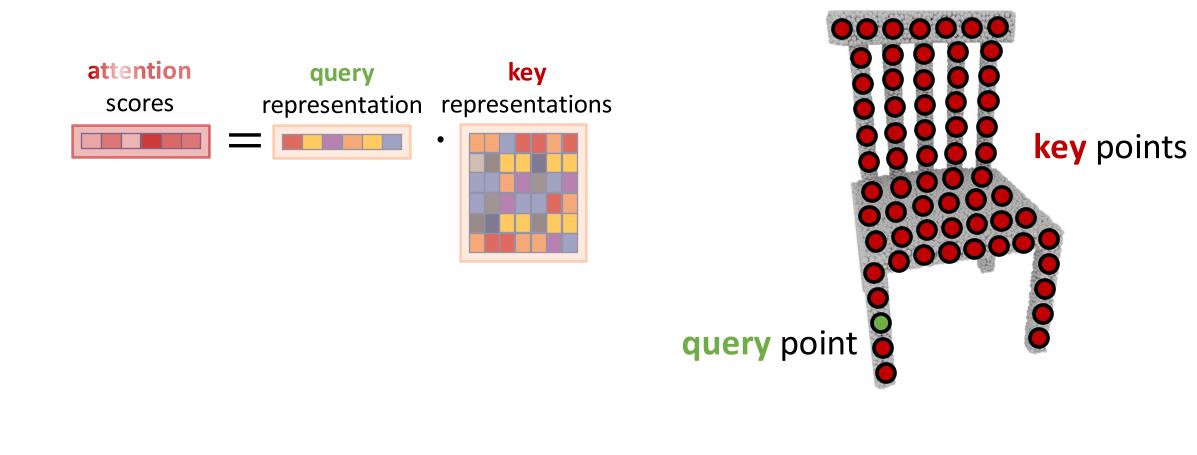
Transformer [Vaswani et al. 2017]

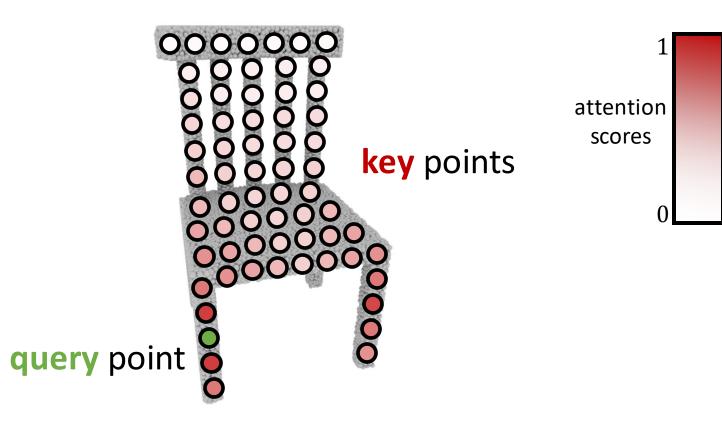


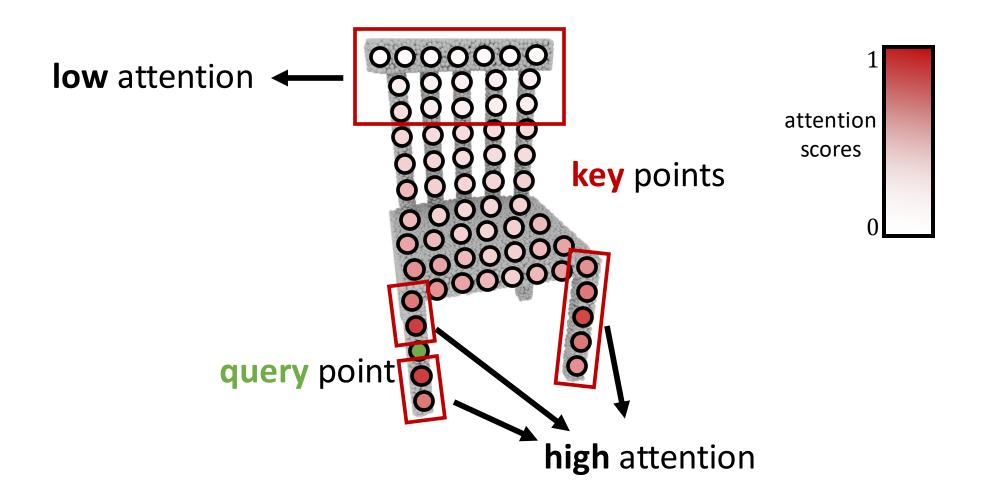


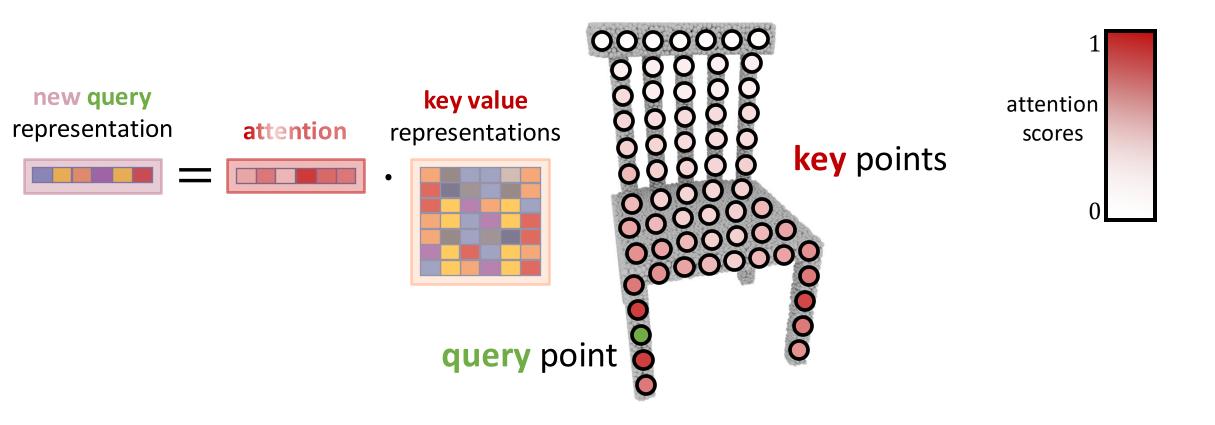


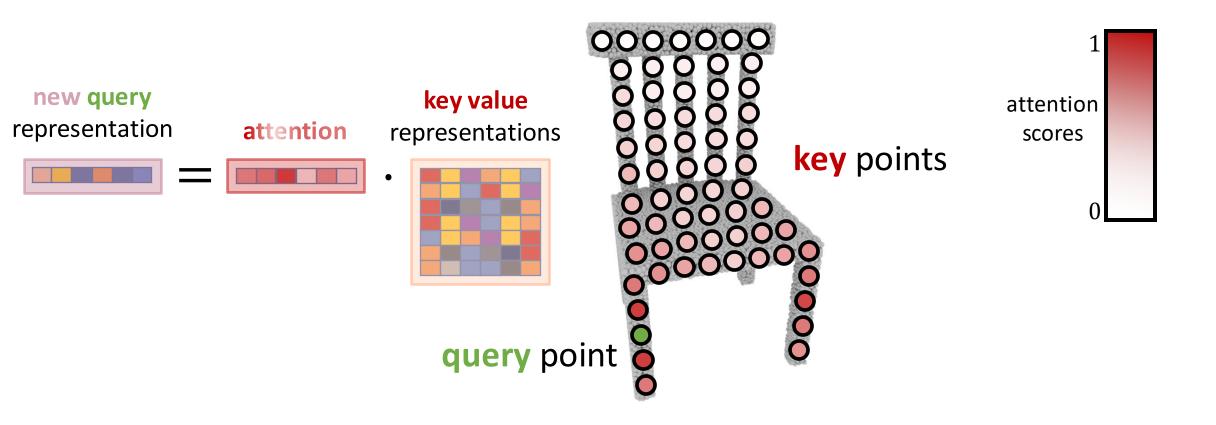


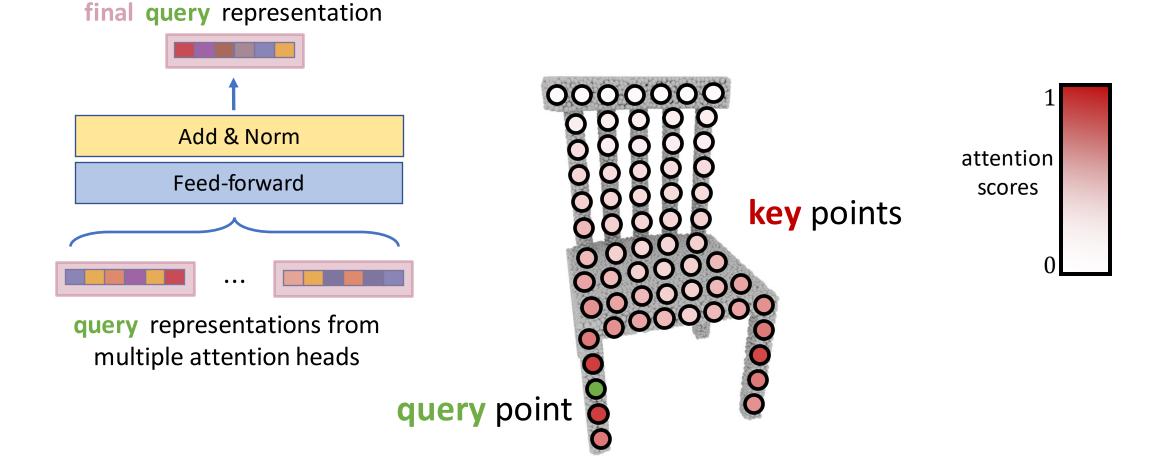












#### Motivation: Long-range interactions across shapes

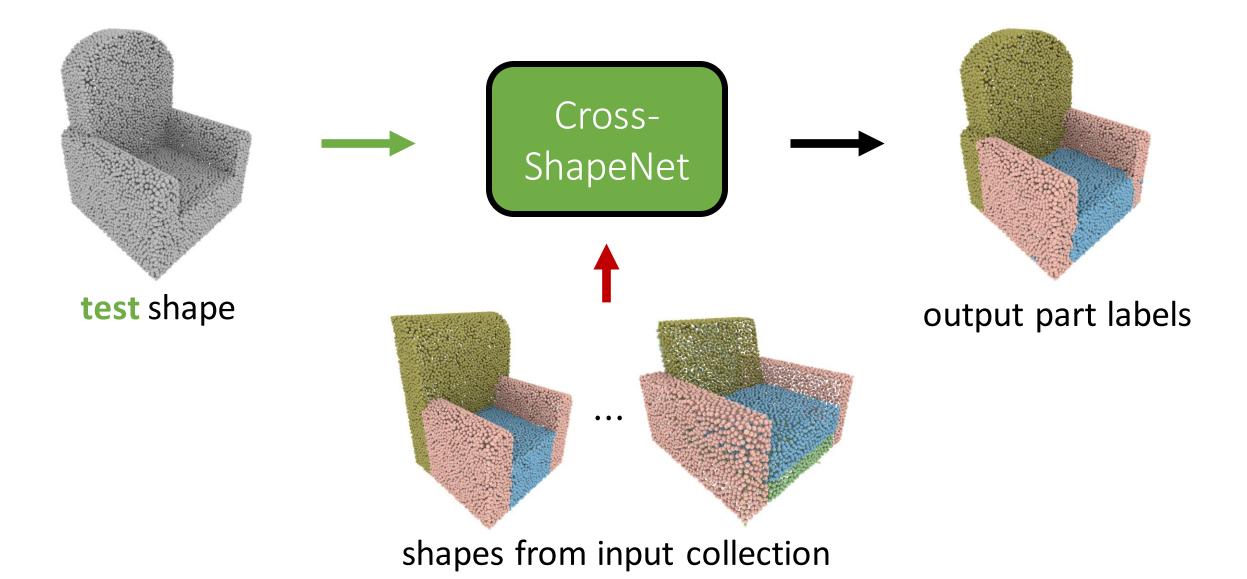


test shape

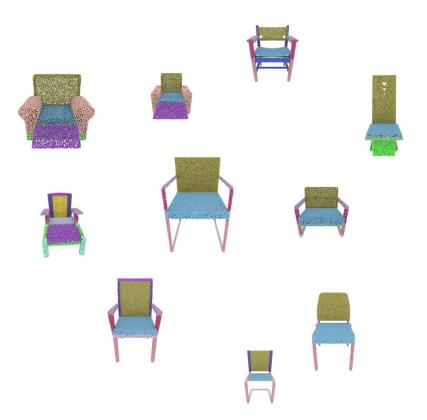
No interactions across shapes

output part labels

#### Motivation: Long-range interactions across shapes

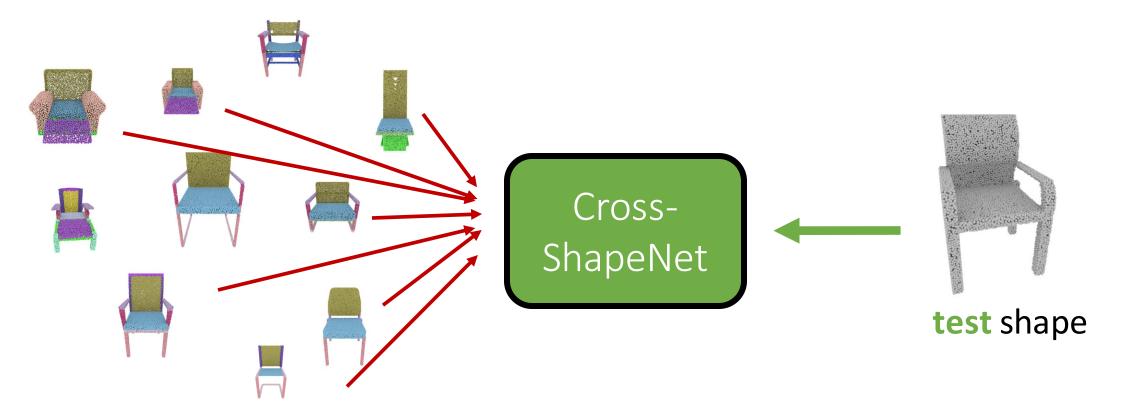


## Key challenge: Retrieve compatible shapes

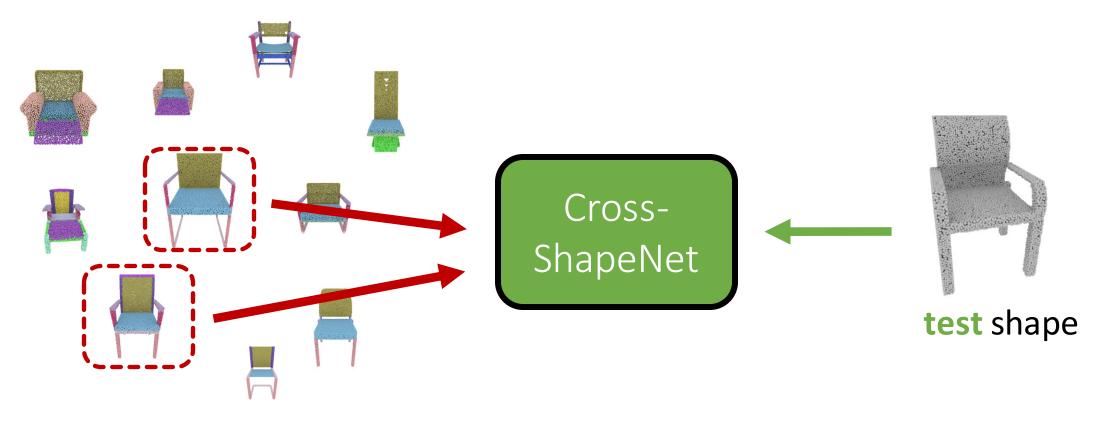




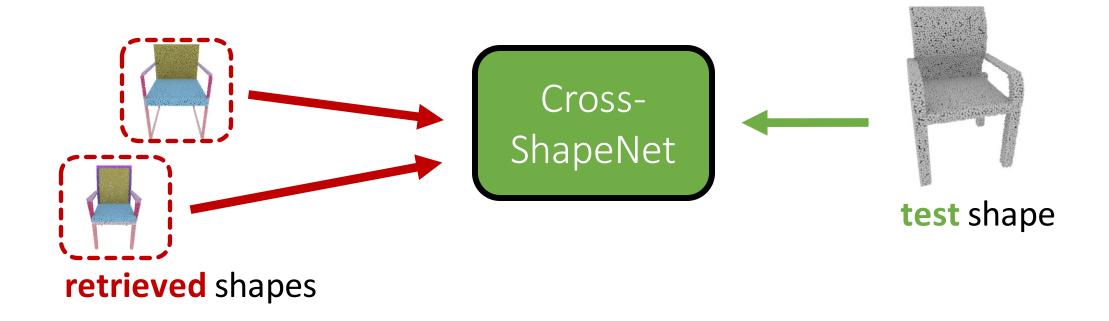
#### Key challenge: Retrieve compatible shapes



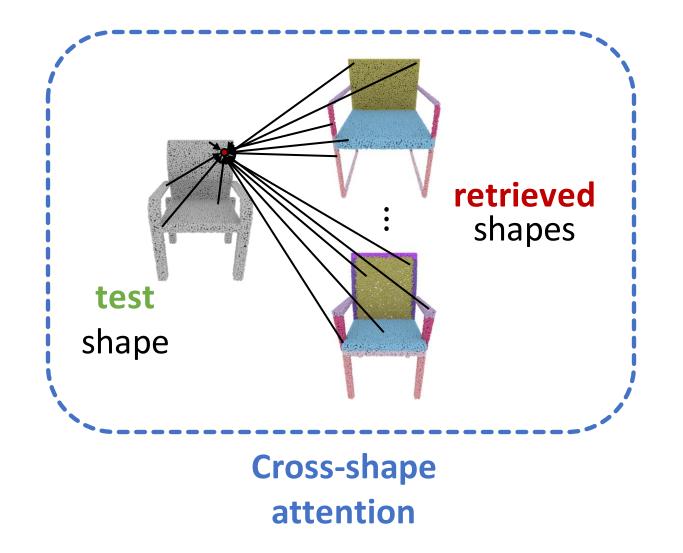
### Key challenge: Retrieve compatible shapes



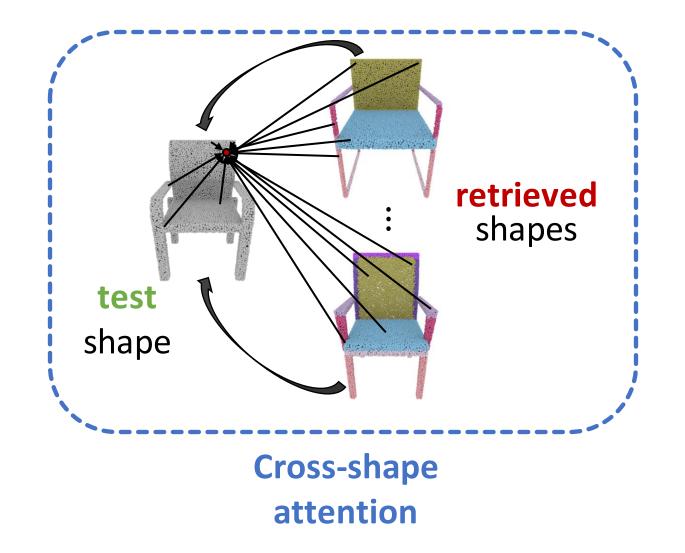
#### Key challenge: Combine multiple shapes

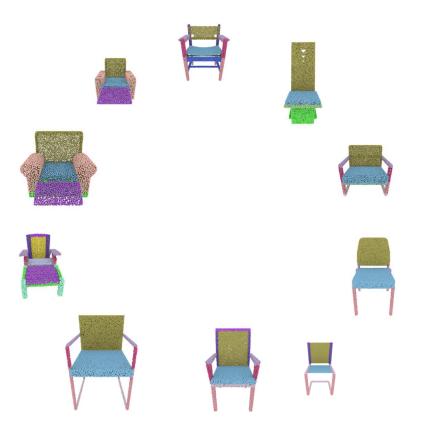


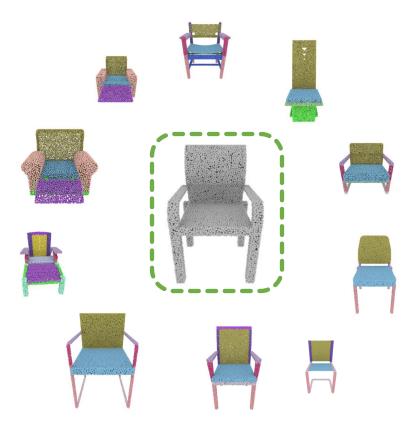
#### Key challenge: Combine multiple shapes

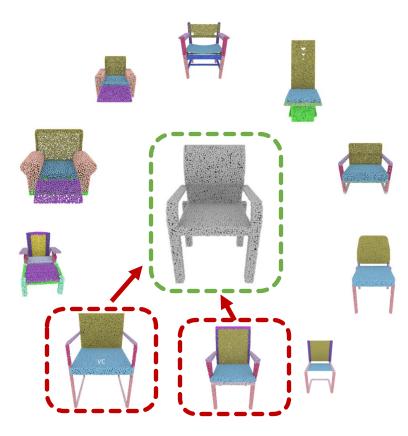


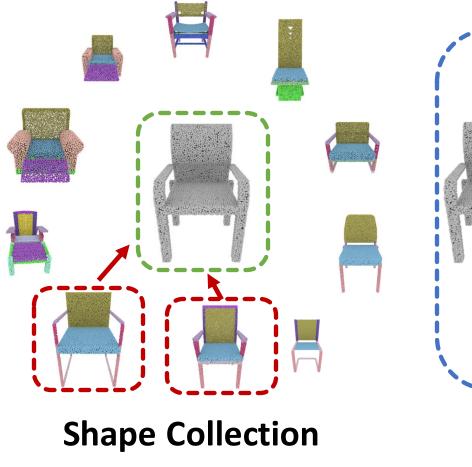
#### Key challenge: Combine multiple shapes

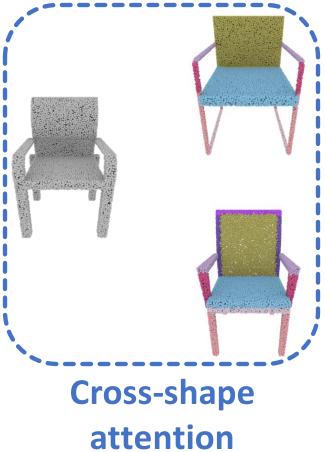


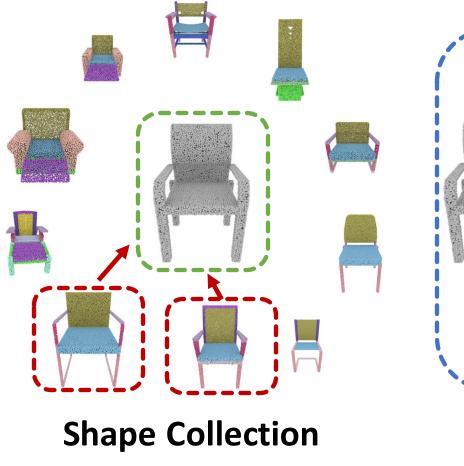


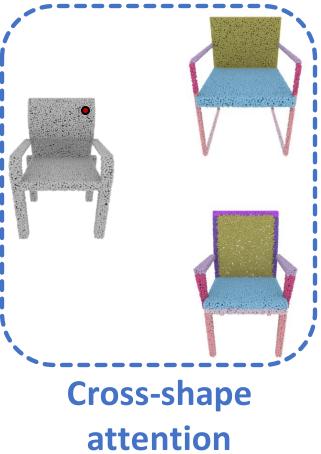


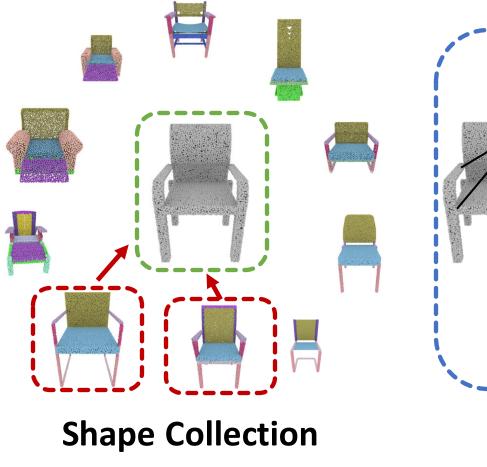


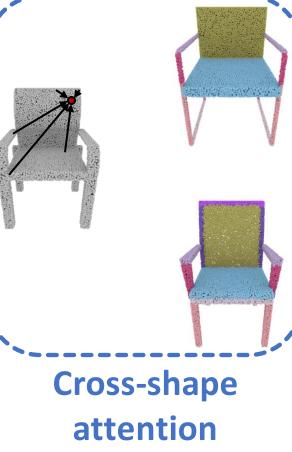


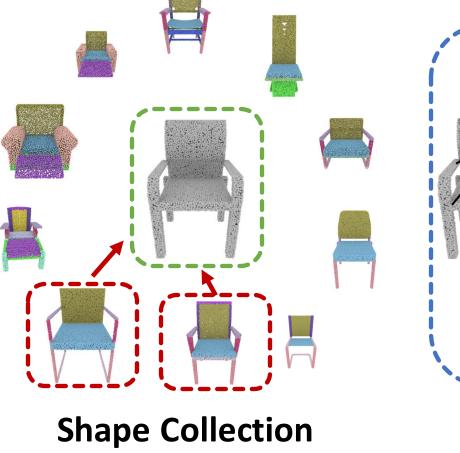


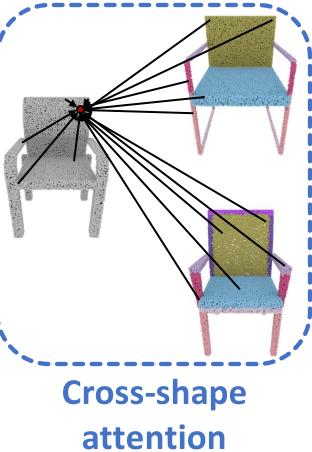




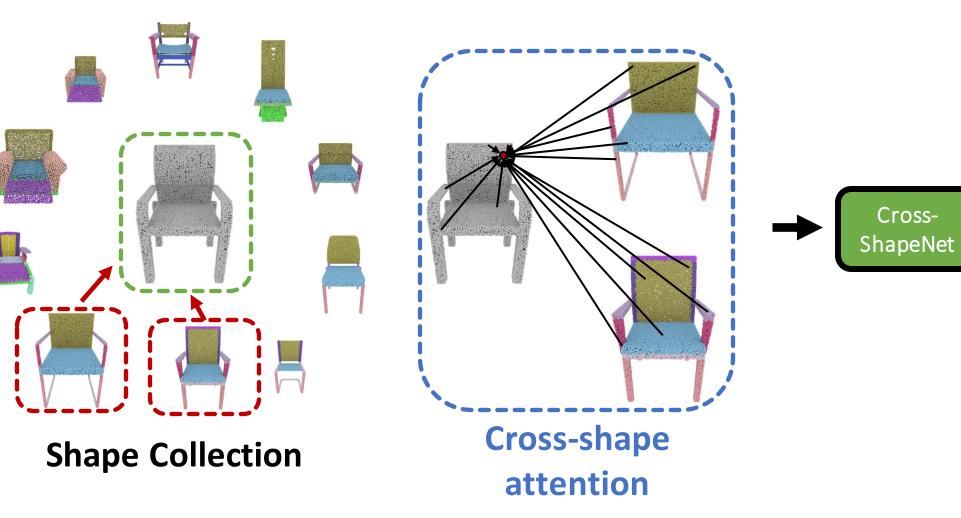




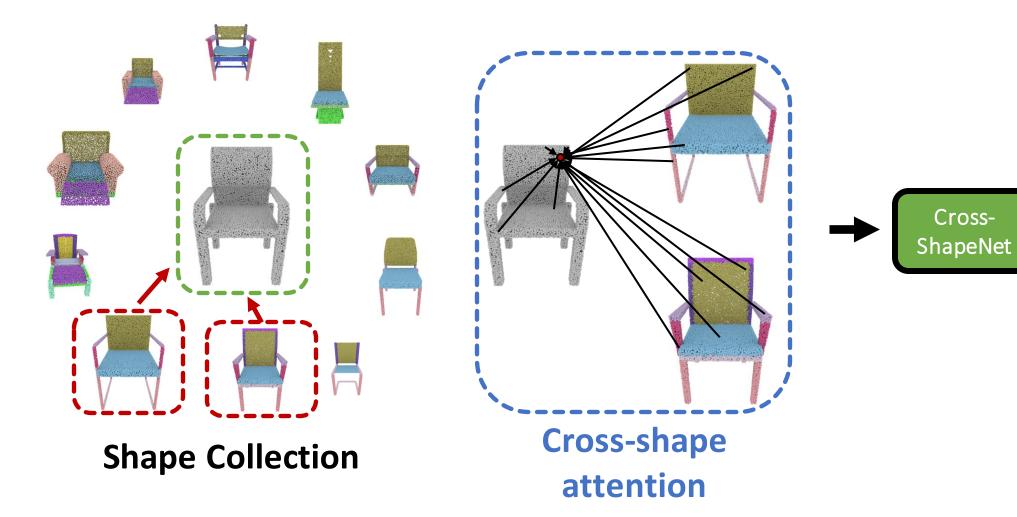




# Pipeline



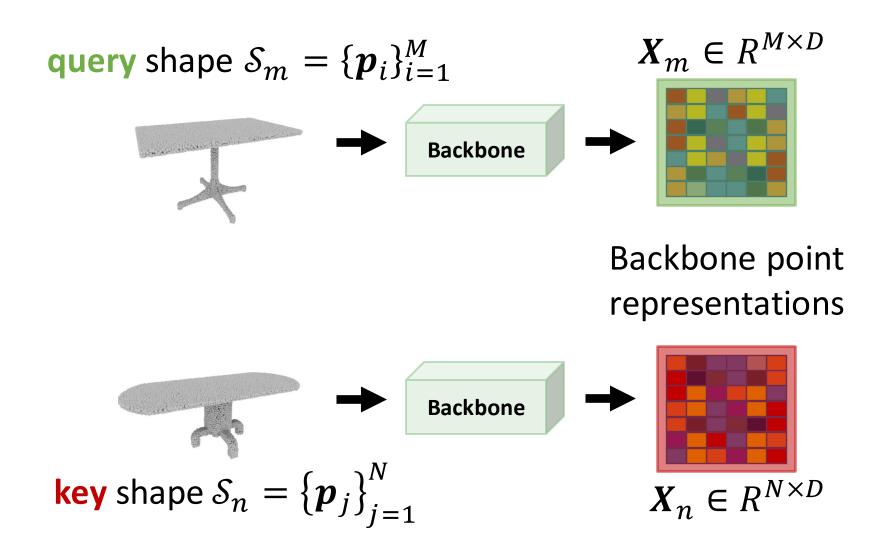
# Pipeline

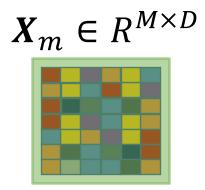


query shape 
$$\mathcal{S}_m = \{ \boldsymbol{p}_i \}_{i=1}^M$$

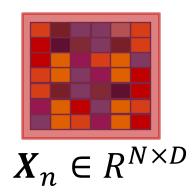


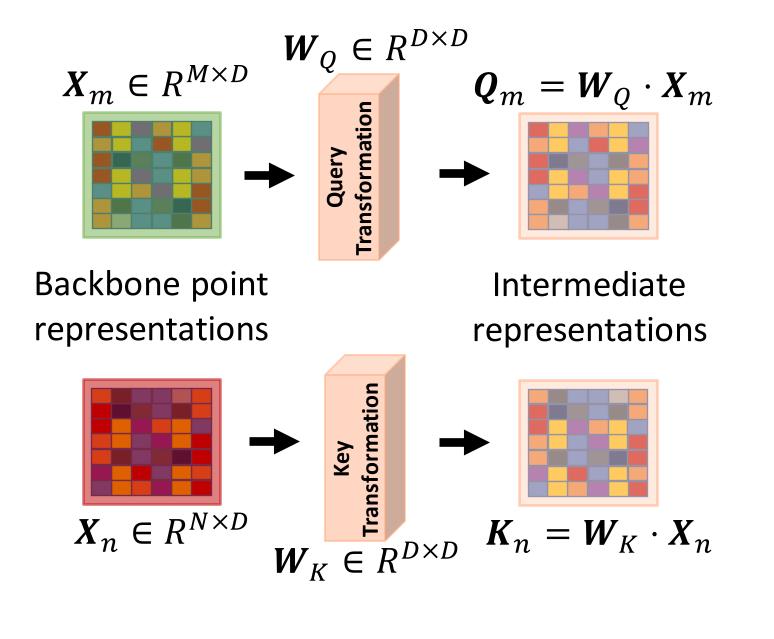
key shape 
$$S_n = \{p_j\}_{j=1}^N$$

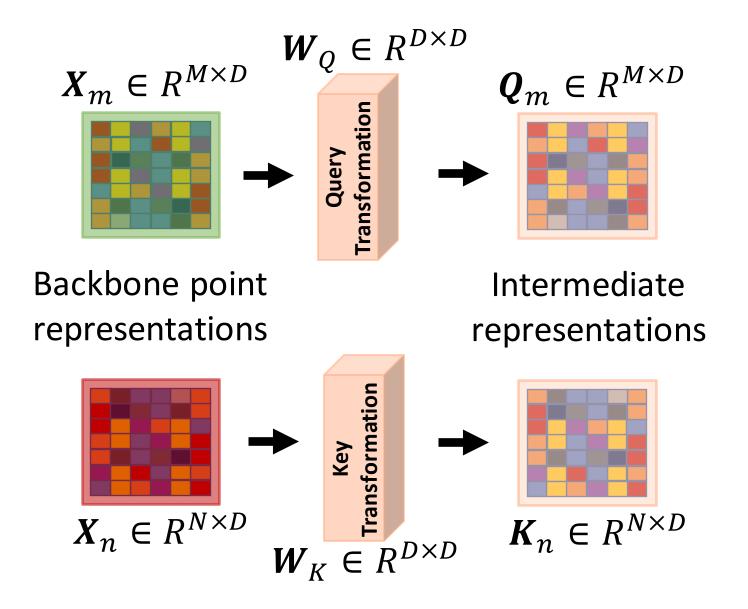


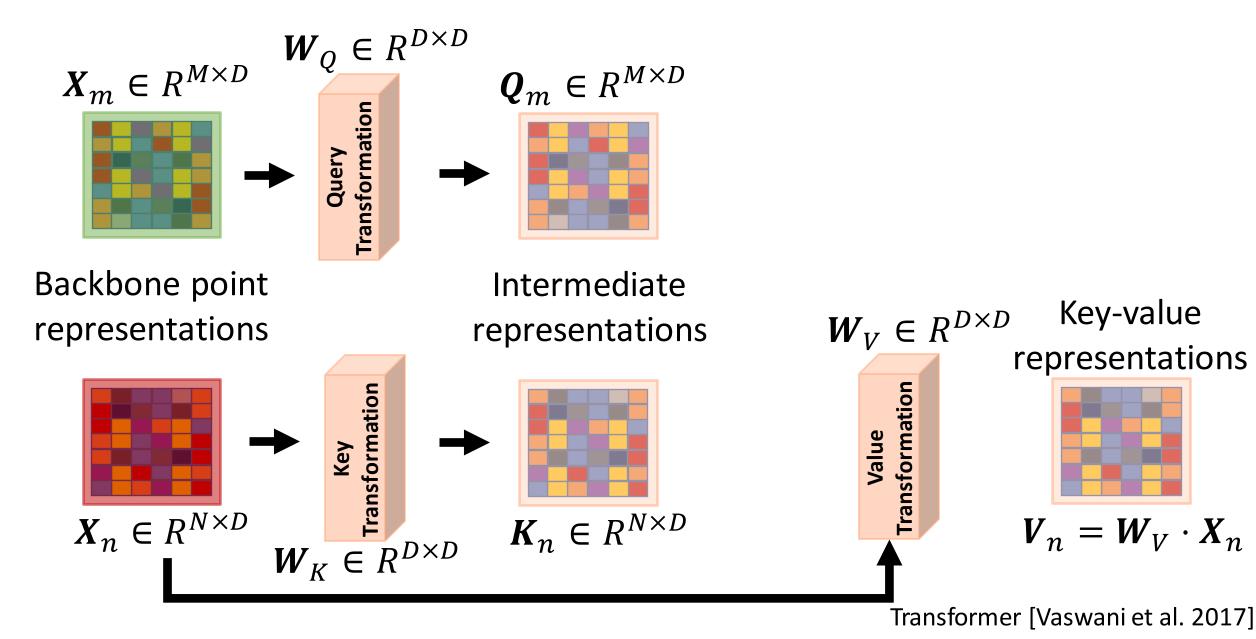


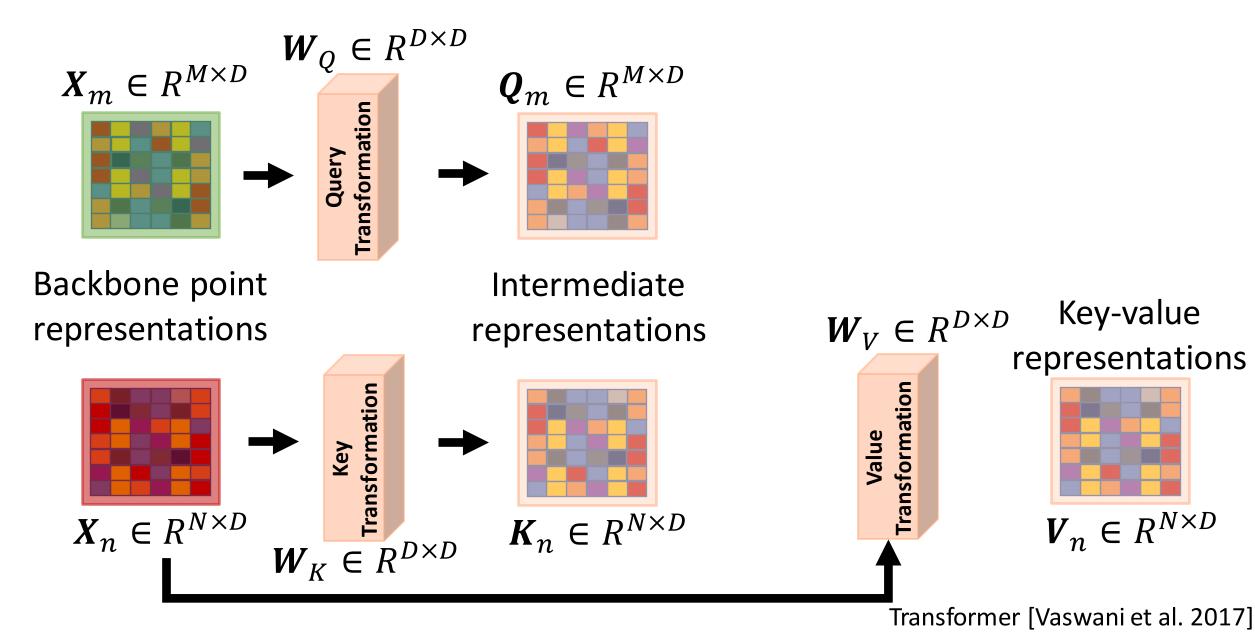
Backbone point representations

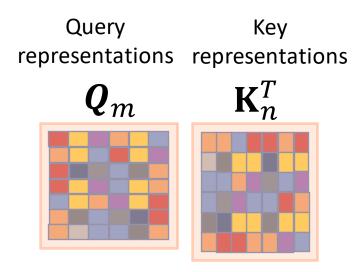


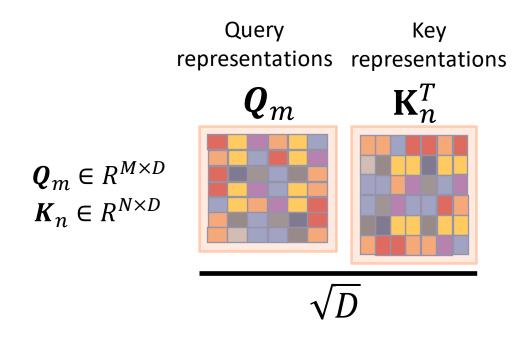


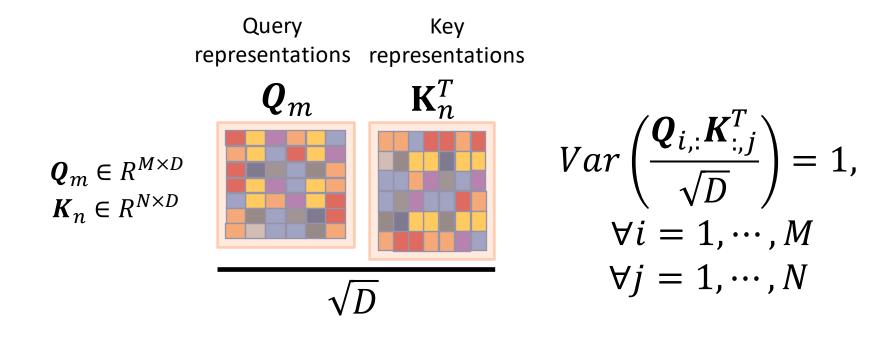


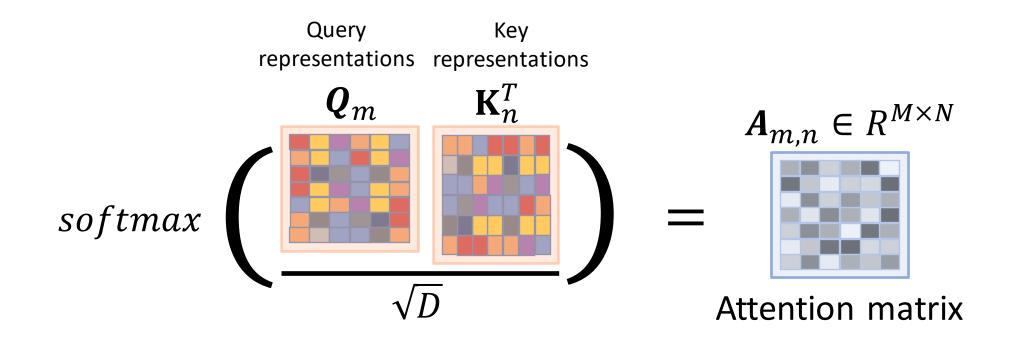


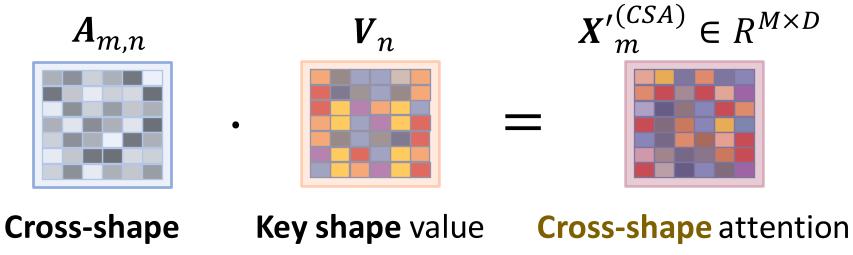








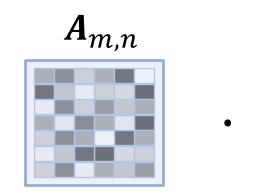


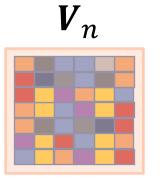


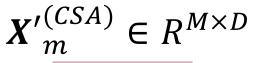
attention matrix

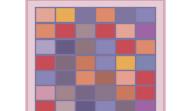
representations

representations



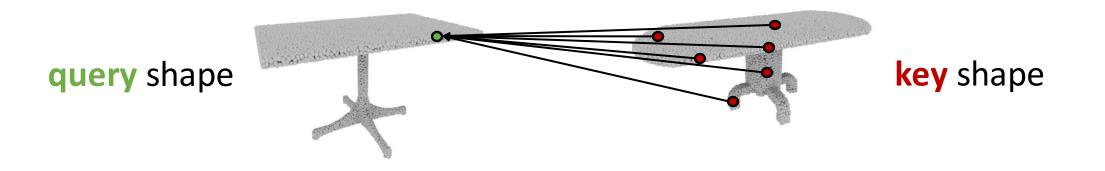


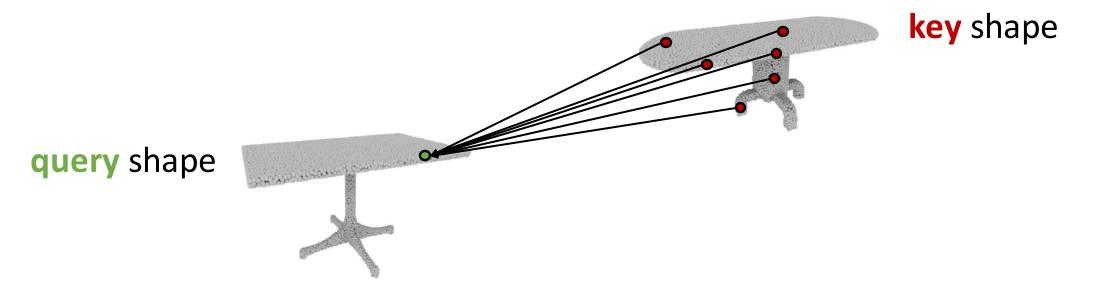


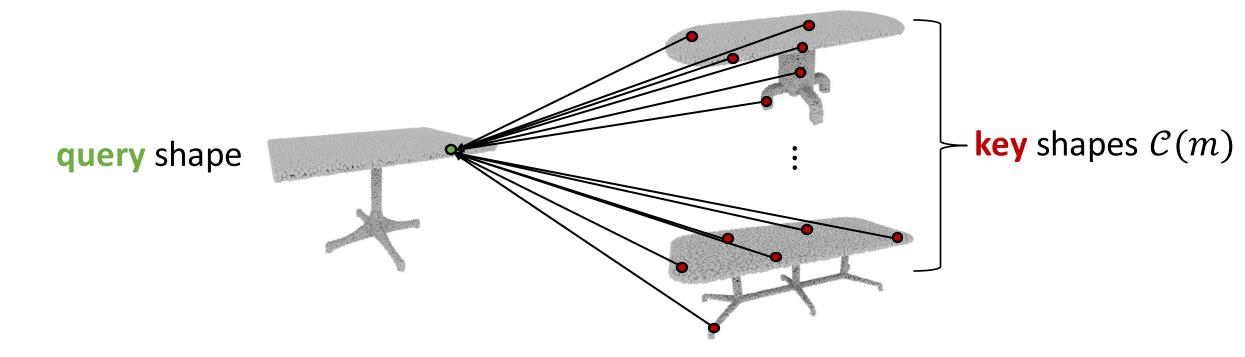


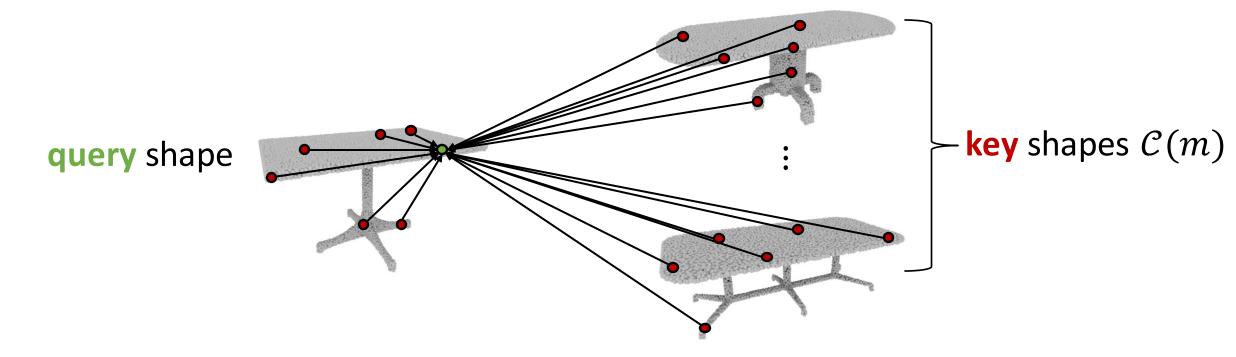
**Cross-shape** attention matrix Key shape value representations

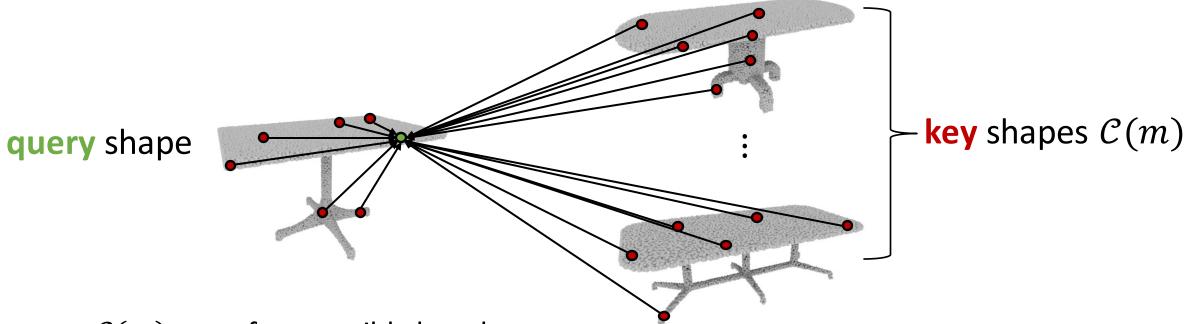
**Cross-shape** attention representations









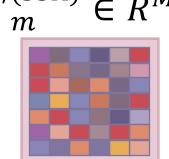


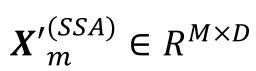
- C(m): set of compatible key shapes
- c(m, n): compatibility function between query shape  $S_m$  and key shape  $S_n$

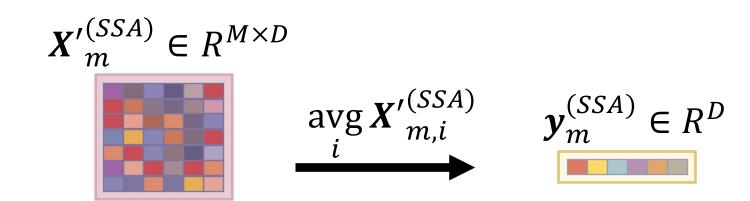
Cross-shape  
attention output 
$$X'_m = \sum_{n \in \{\mathcal{C}(m), m\}} c(m, n) A_{m,n} V_n$$

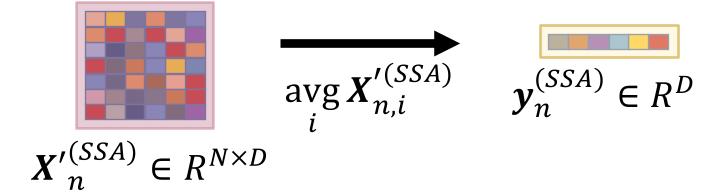
 $X'_n^{(SSA)} \in R^{N \times D}$ 

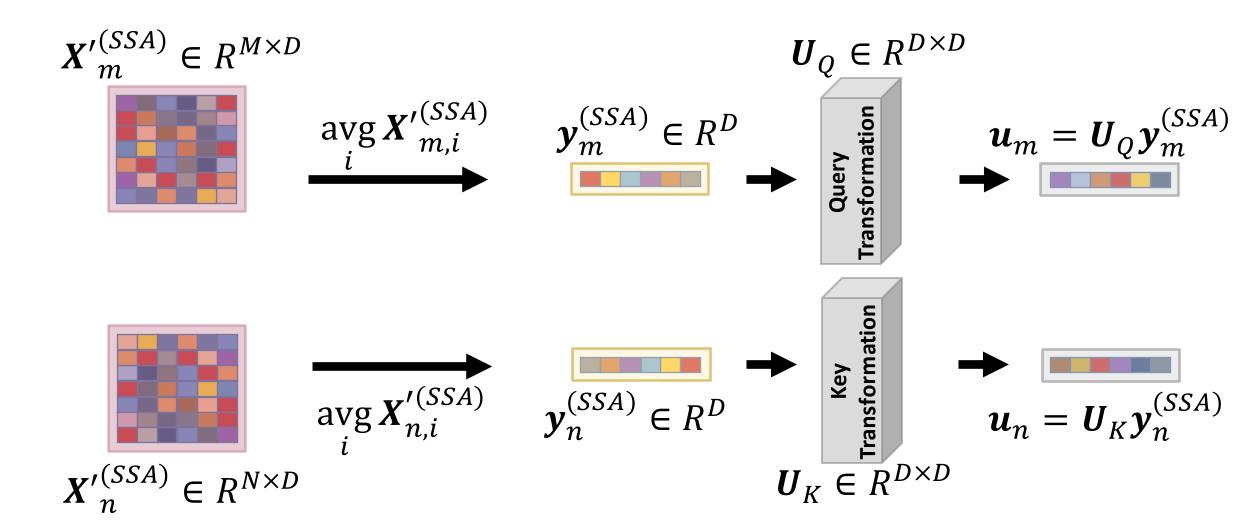


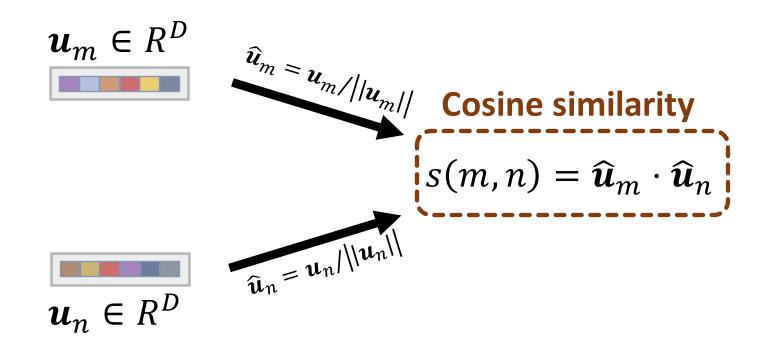


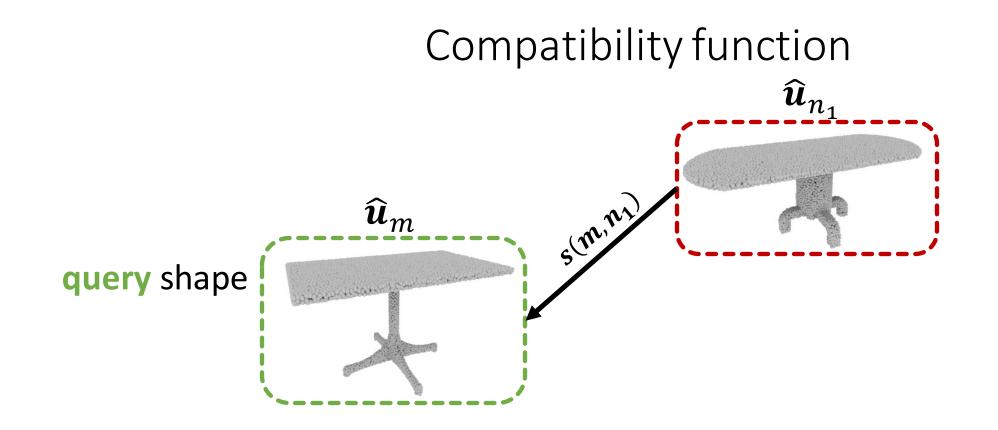


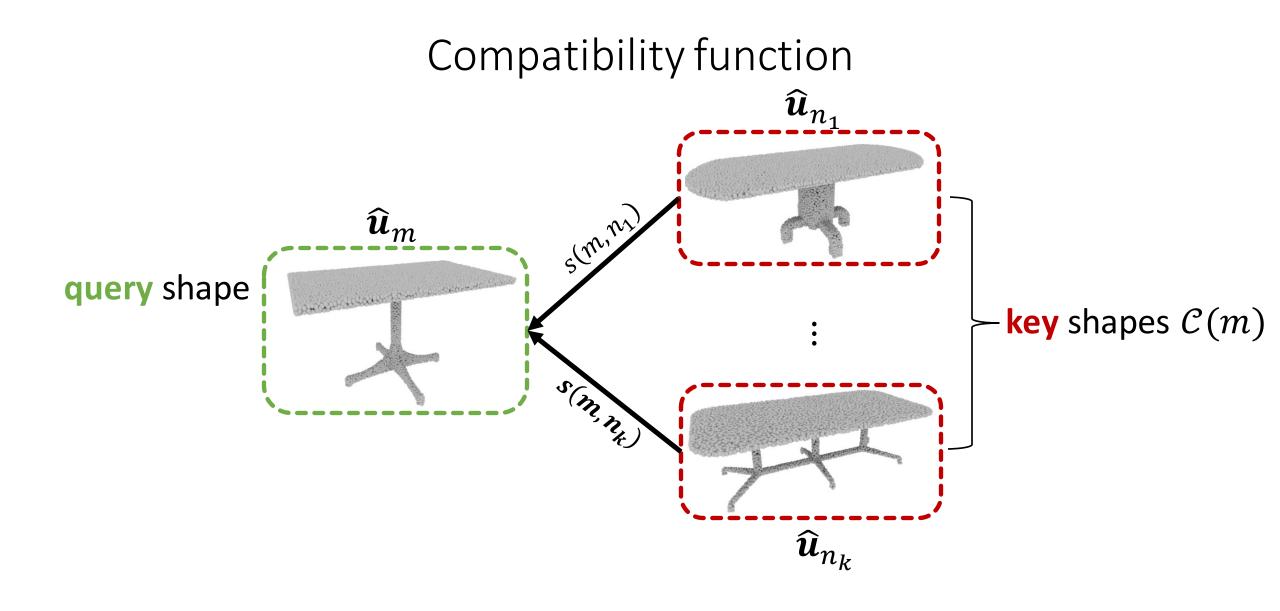


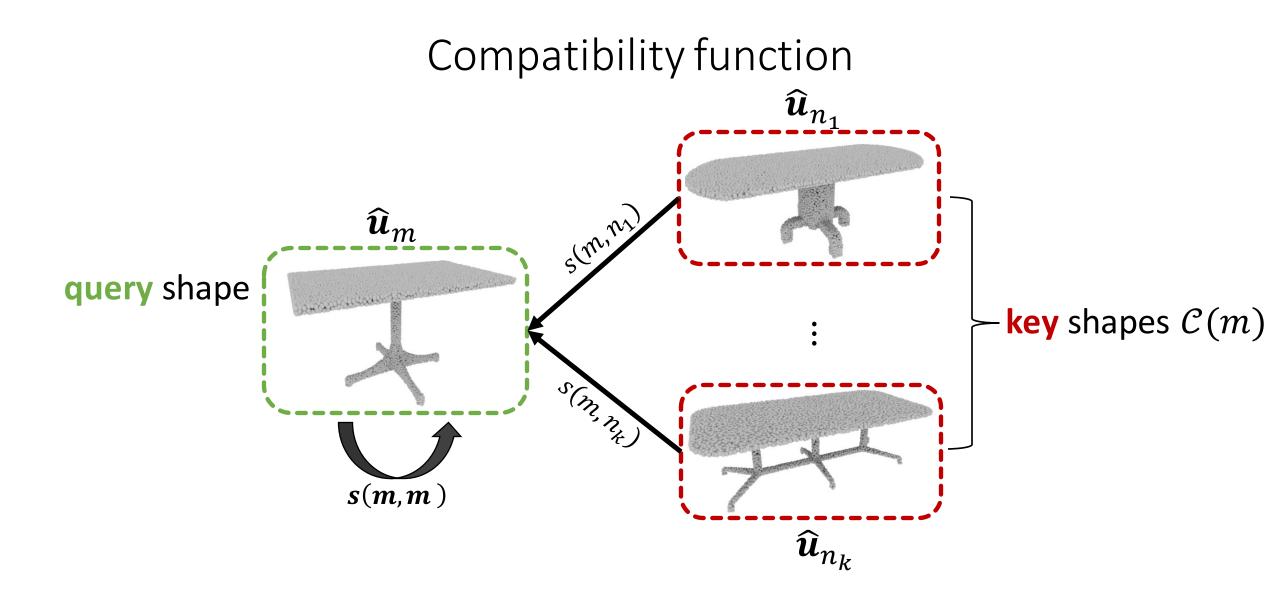


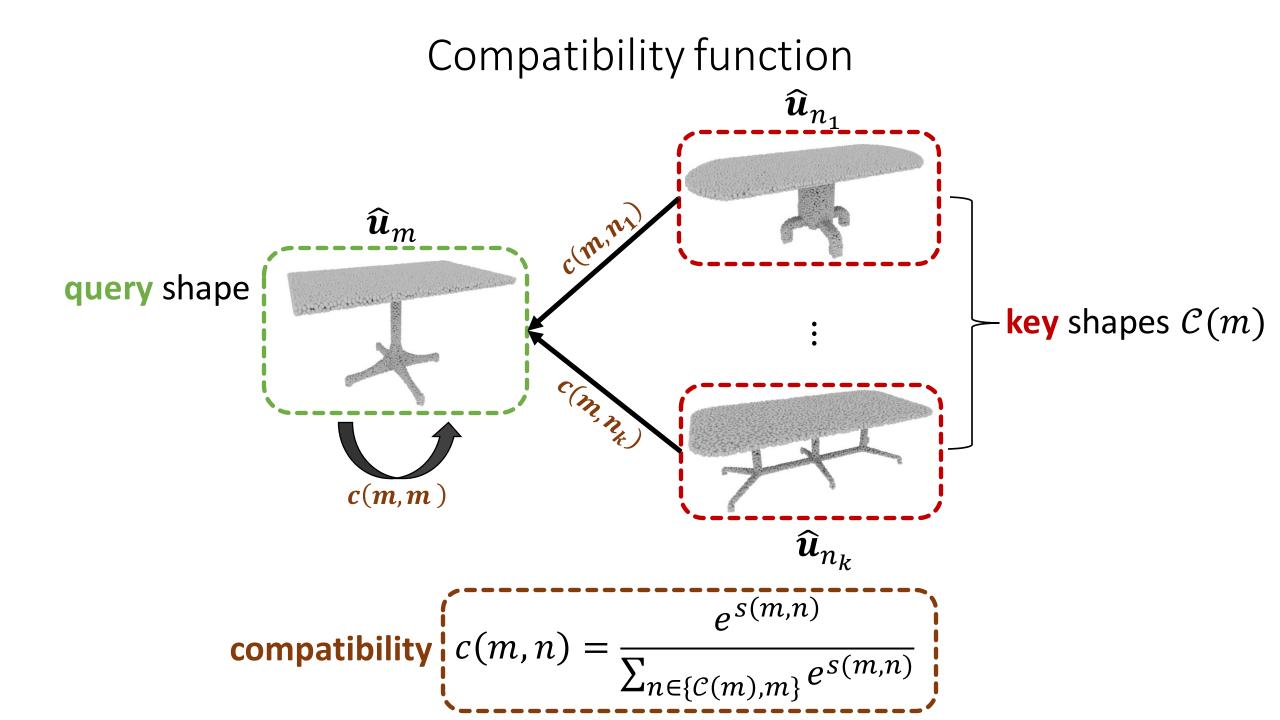


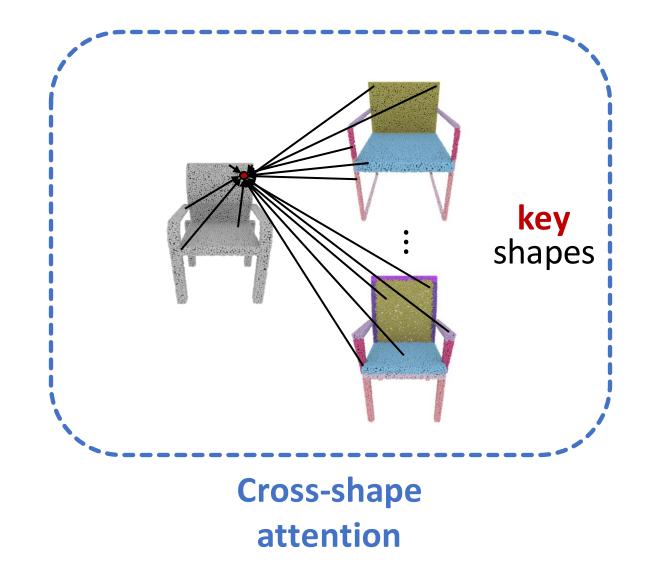


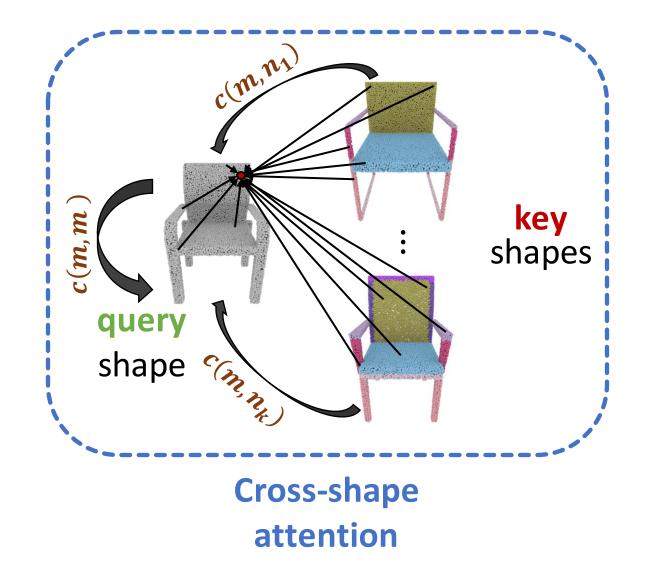




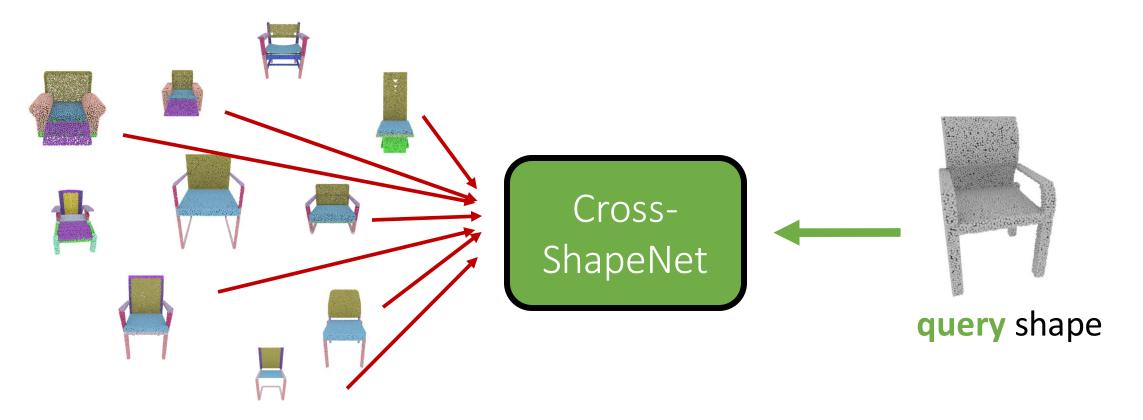






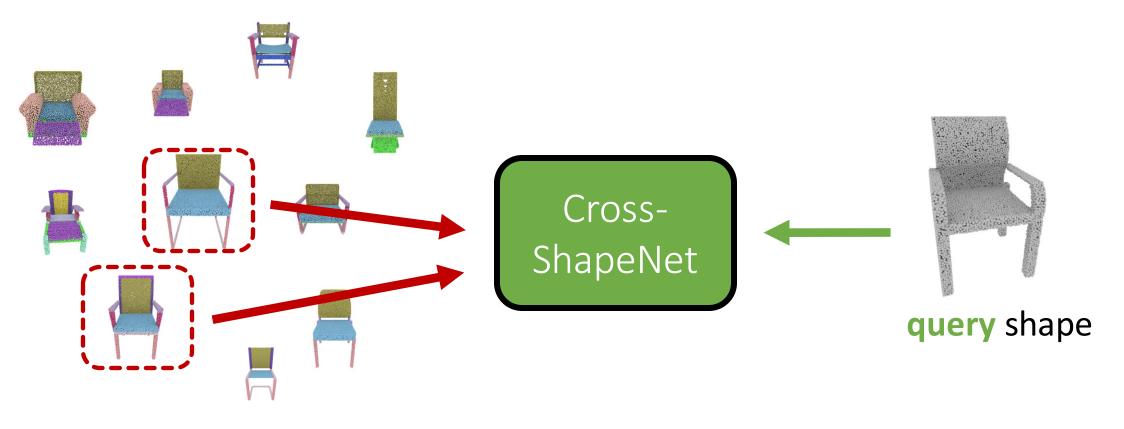


# Retrieve compatible shapes



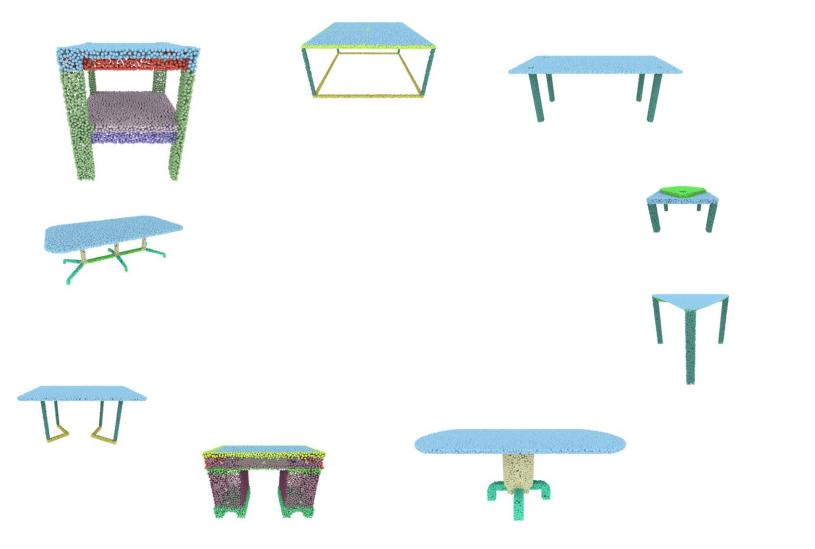
**Shape Collection** 

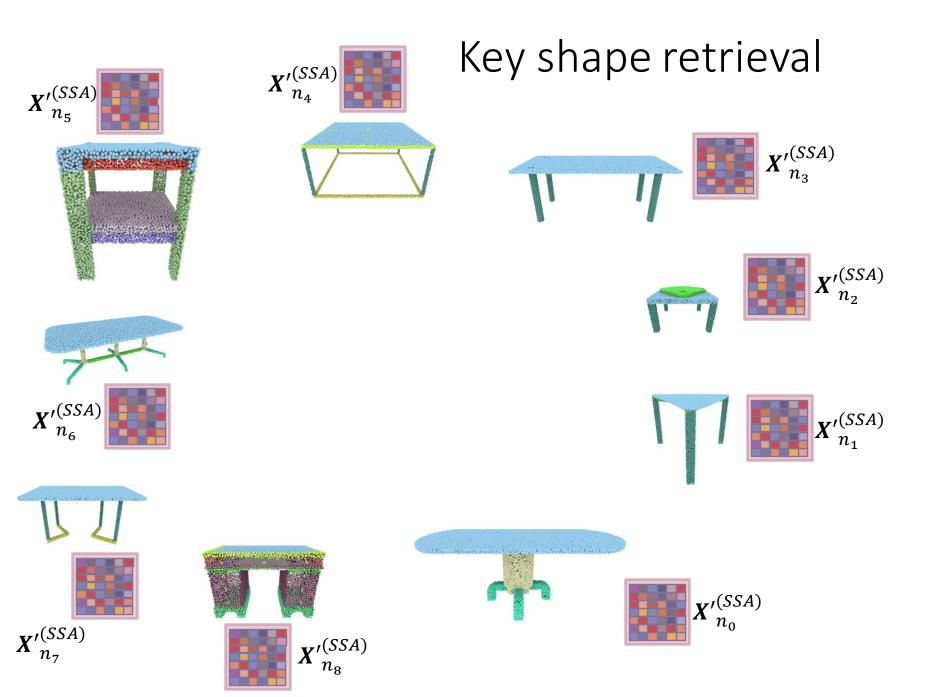
# Retrieve compatible shapes

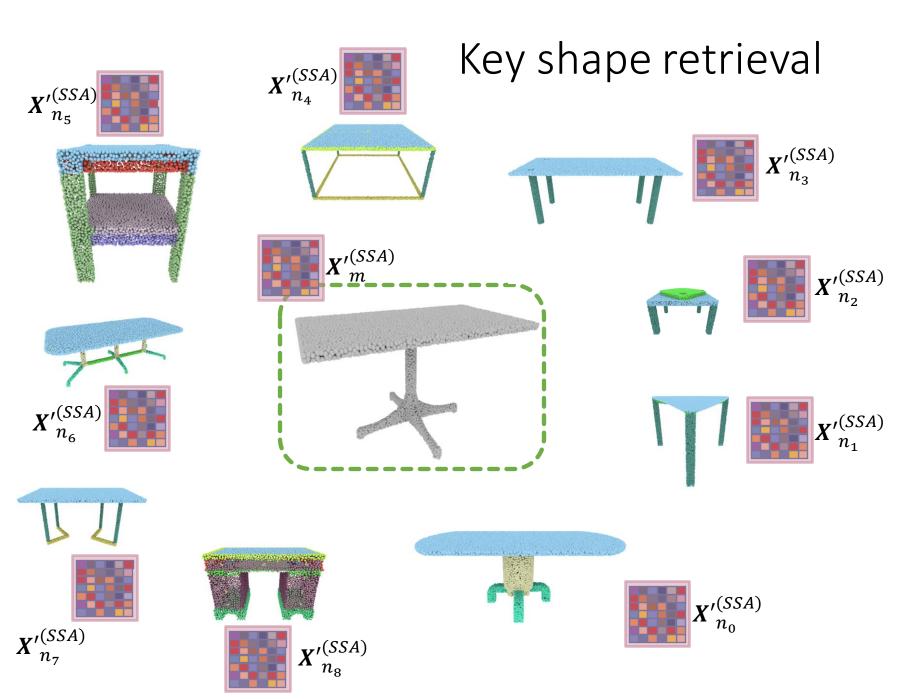


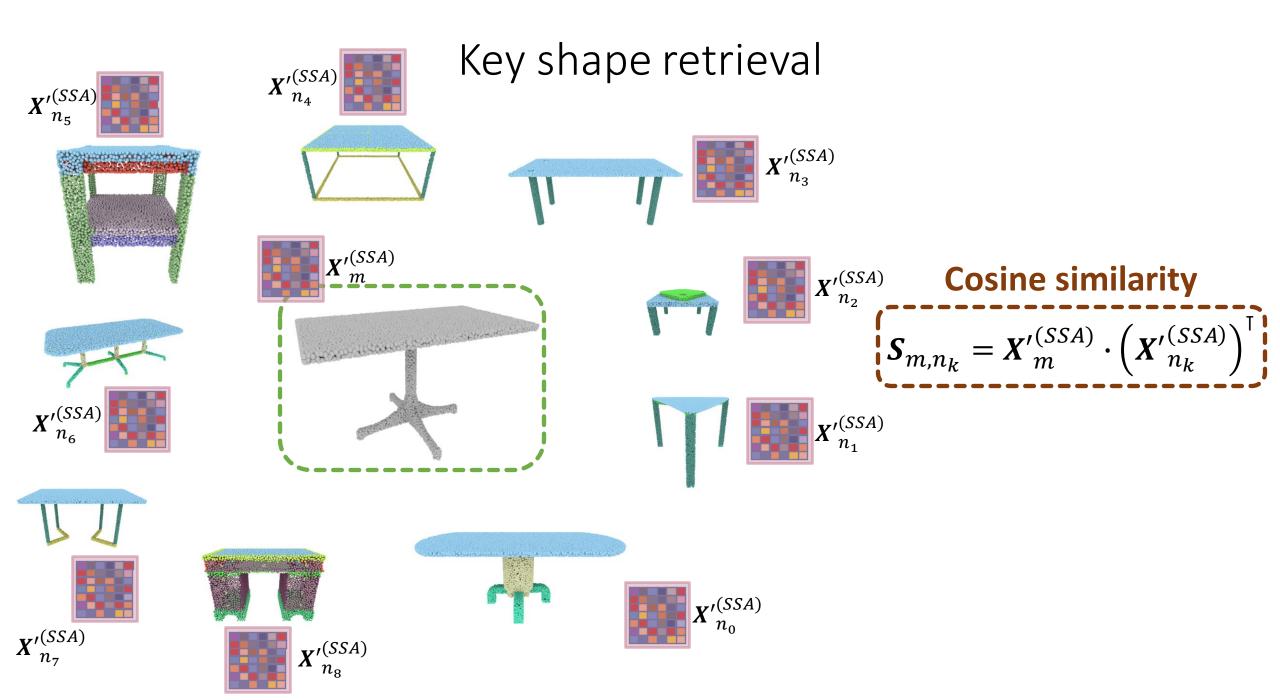
**Shape Collection** 

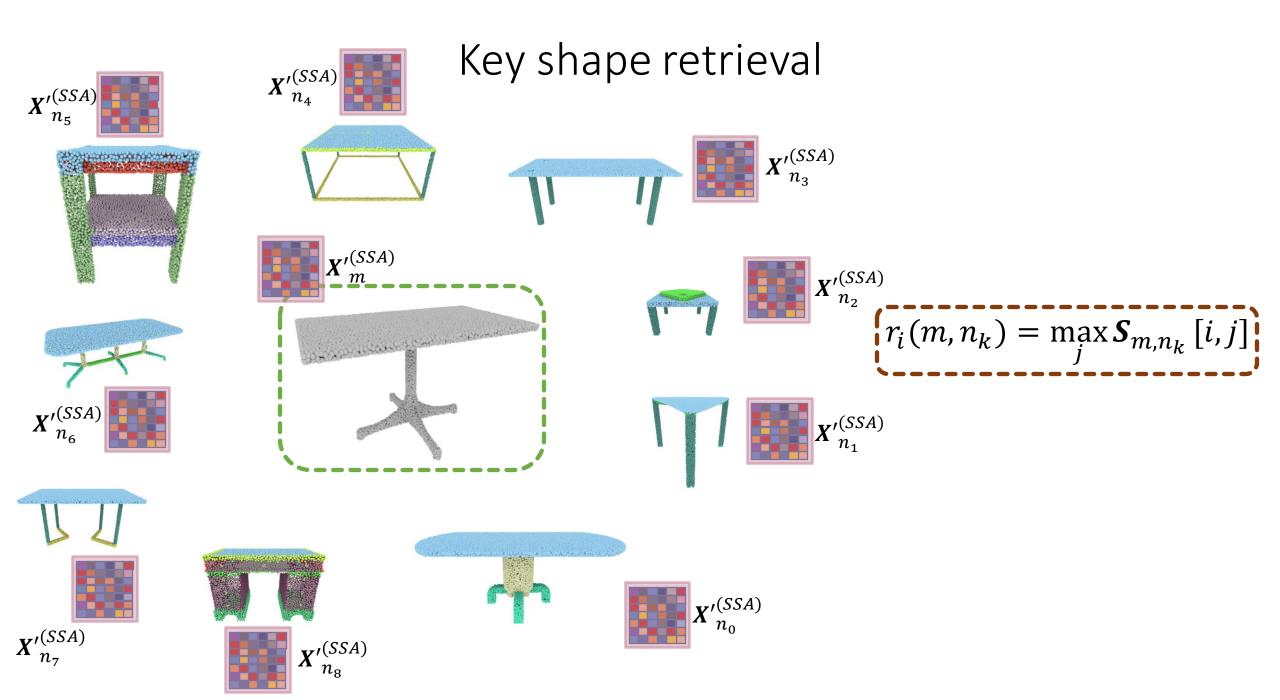
# Key shape retrieval

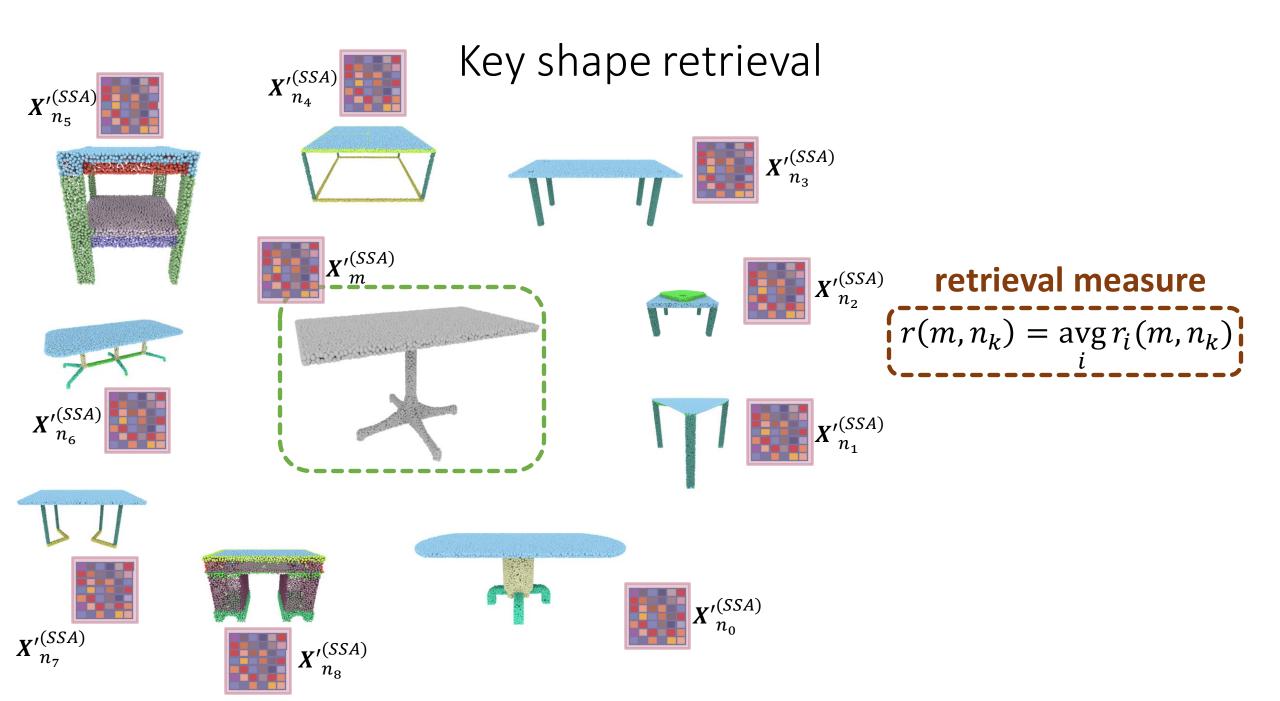


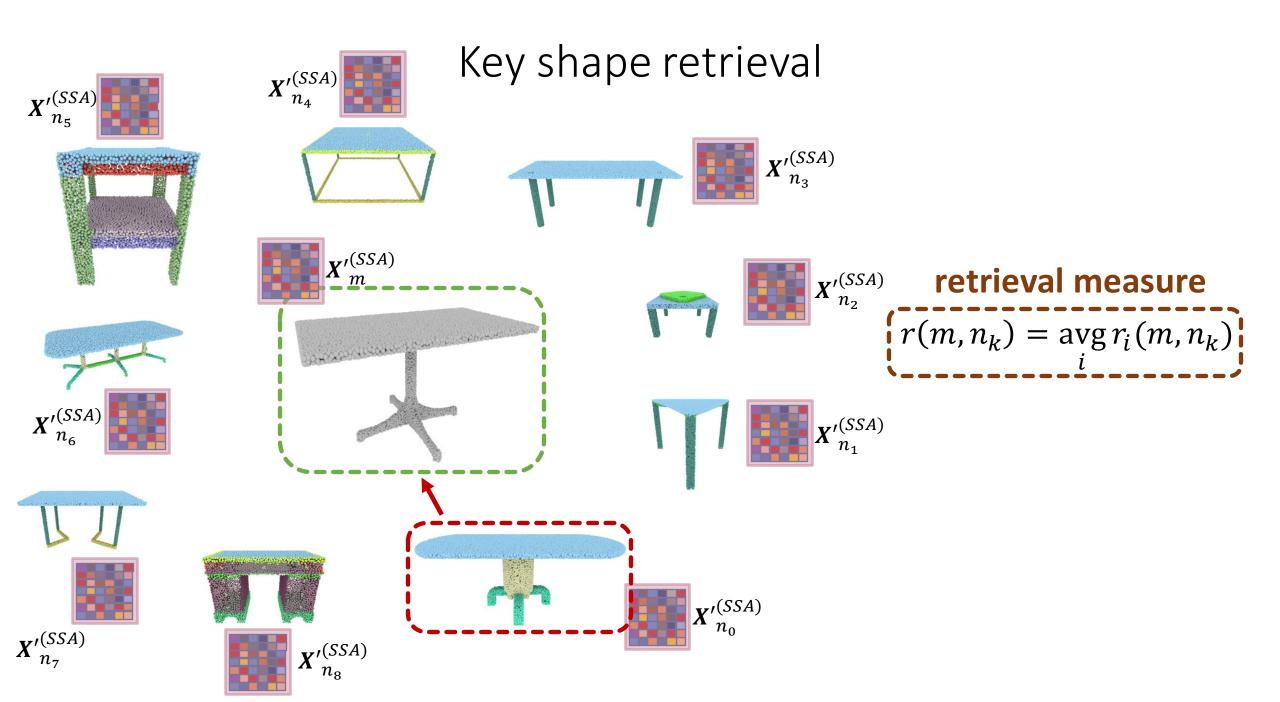


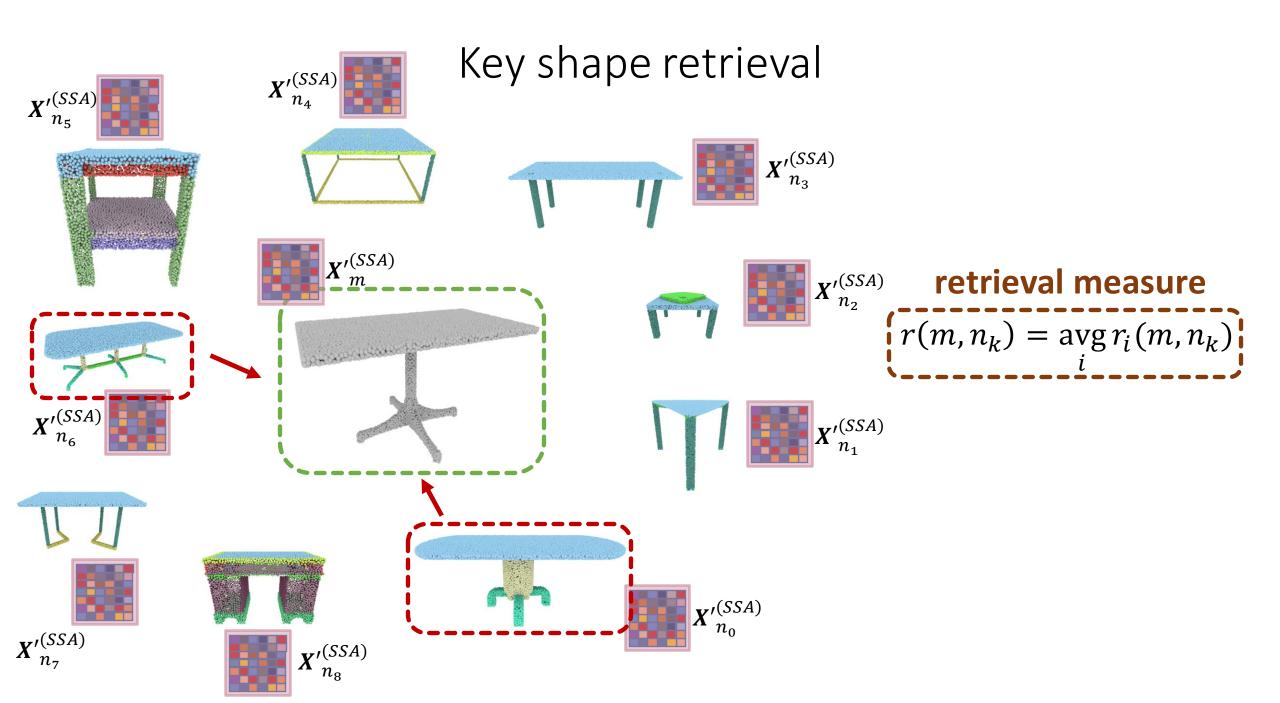






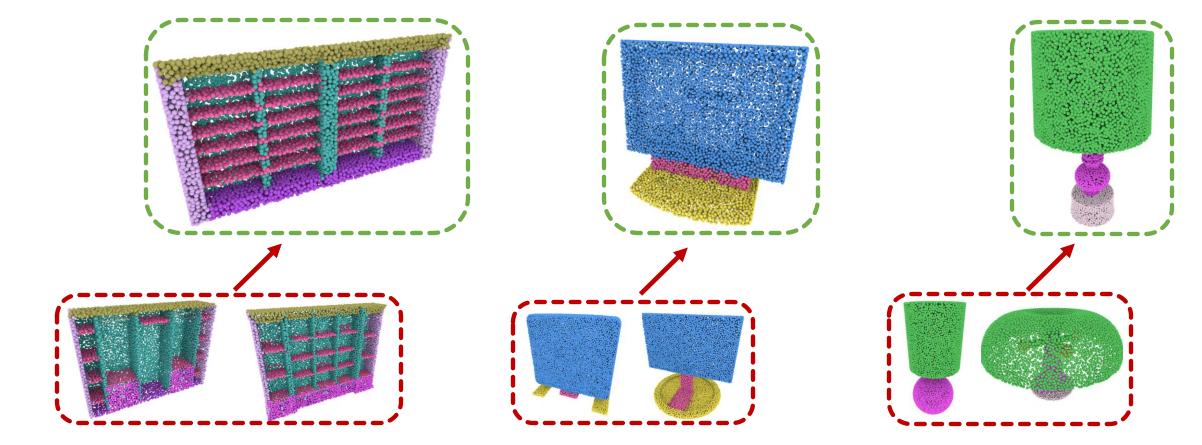




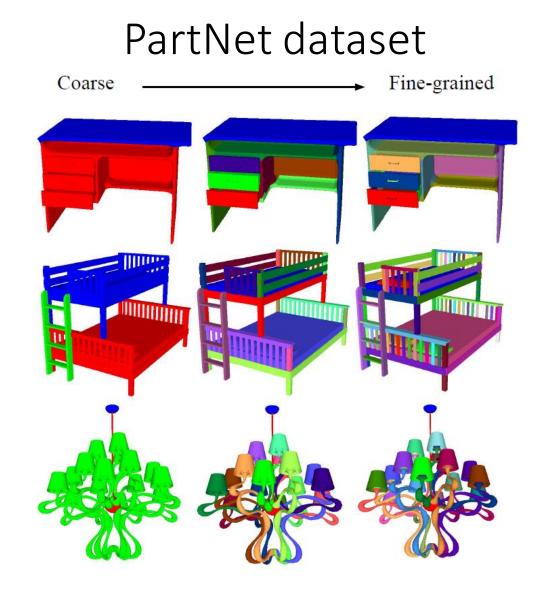


### Key shape retrieval: Examples

query shapes

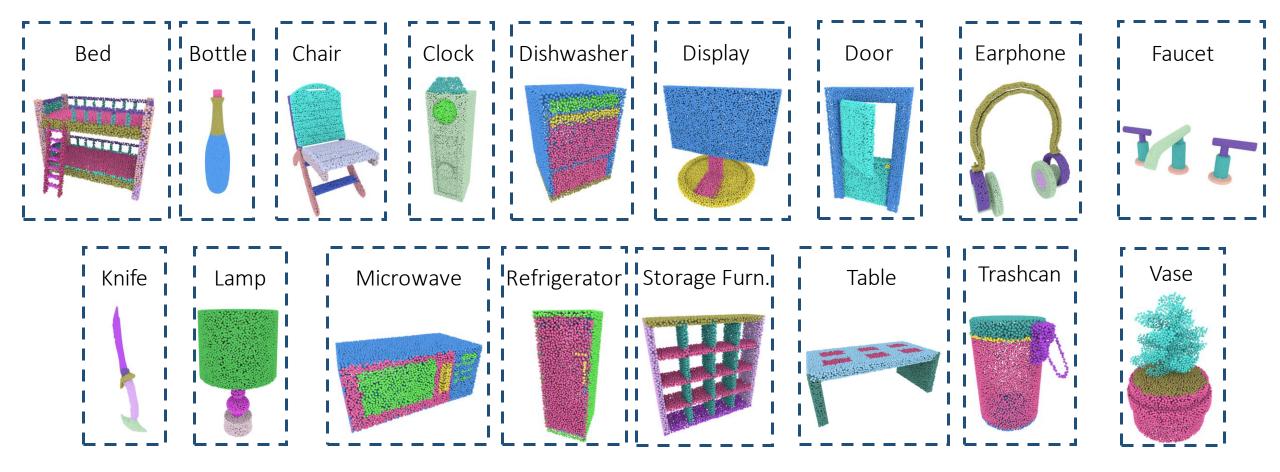


key shapes



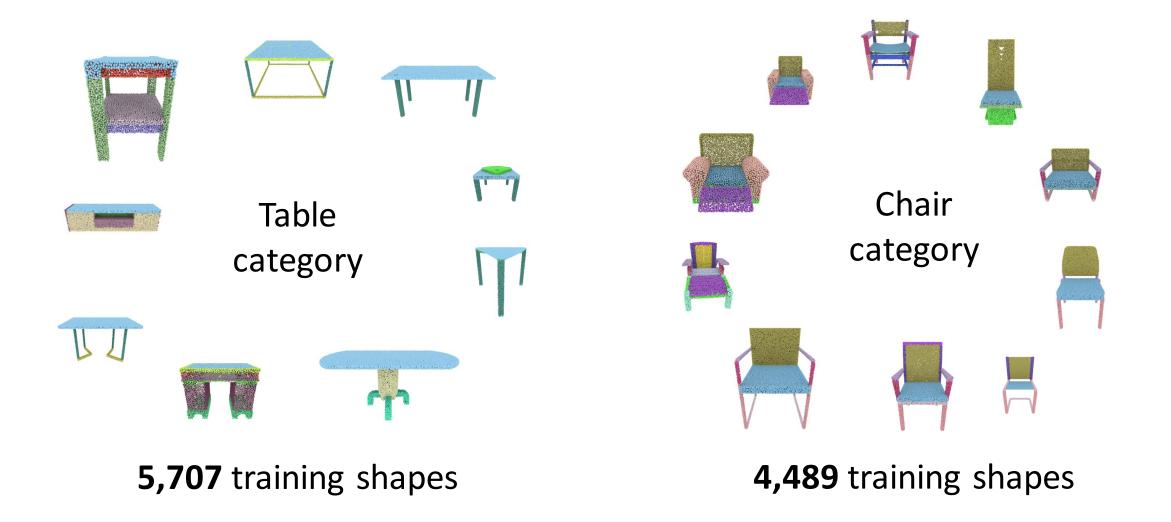
[Moetal. 2019]

### PartNet dataset



[Moetal. 2019]

### Examples of shape collections







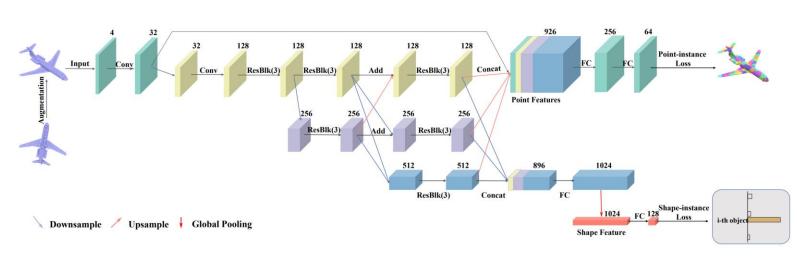
### Training details: Loss

$$L_{CE} = -\sum_{\boldsymbol{p}_i \in \mathcal{S}_k} \widehat{\boldsymbol{q}}_i \log \boldsymbol{q}_i$$

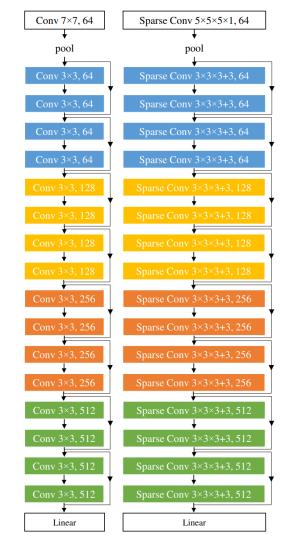
 $S_k$ : shape  $k = \{\boldsymbol{p}_i\}_{i=1}^{P_k}$ 

 $\widehat{q}_i$ : ground-truth one-hot label vector for point  $p_i$  $q_i$ : predicted label probabilities for point  $p_i$ 

### Training details: Backbones

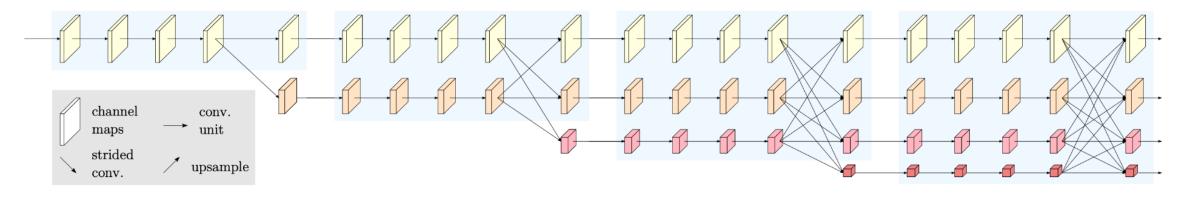


MID-FC [Wang et al. 2021]

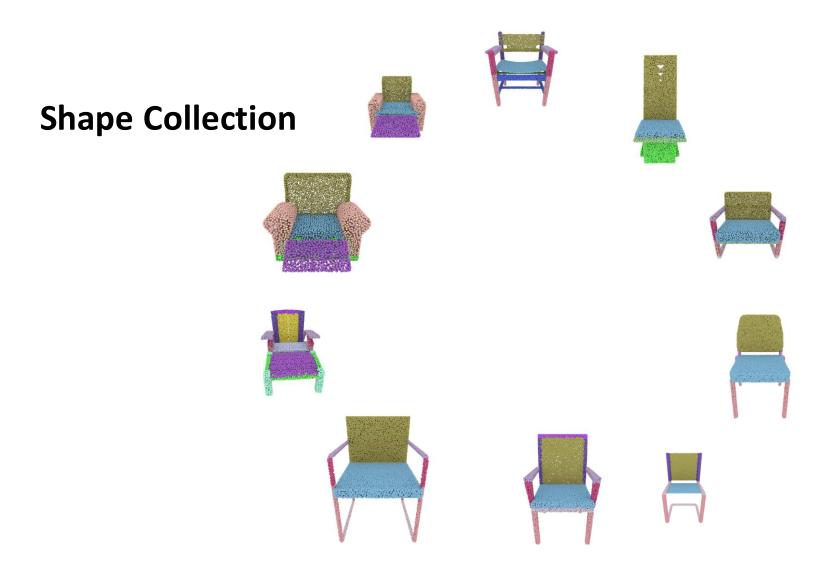


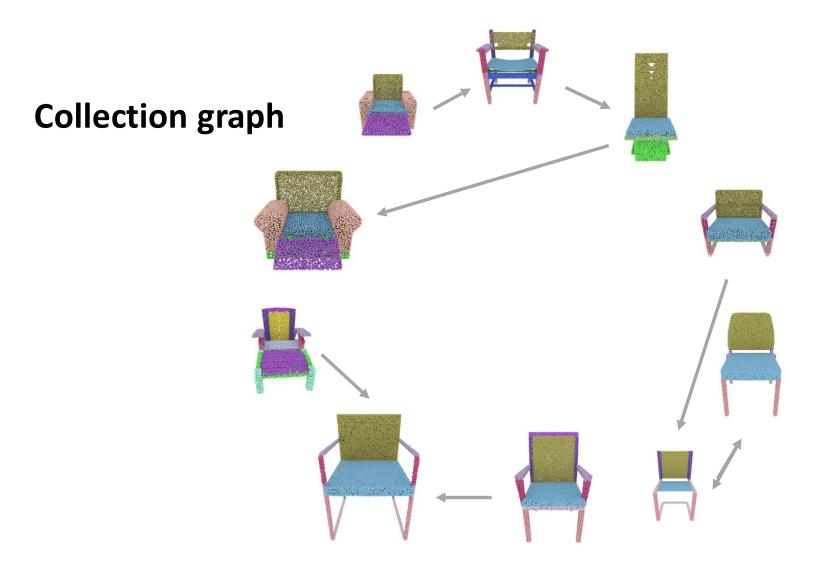
MinkowskiNet [Choy et al. 2019]

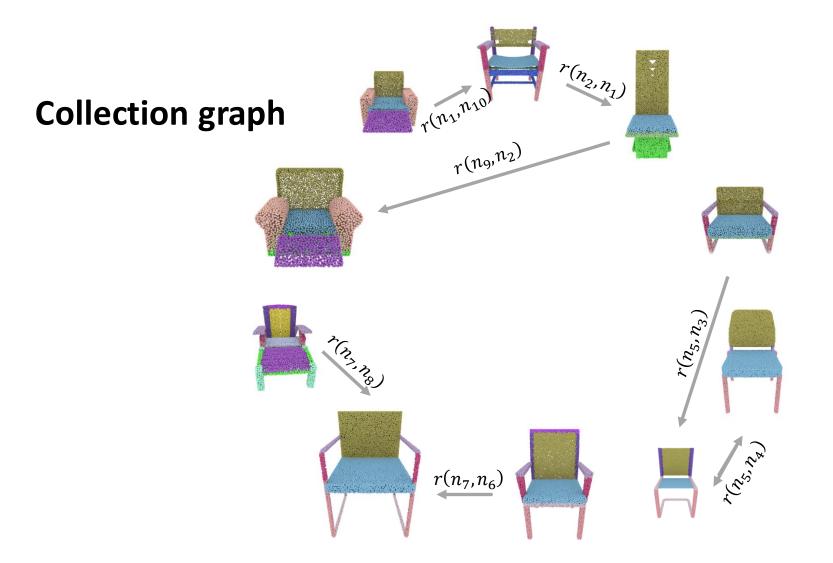
### Training details: Backbones

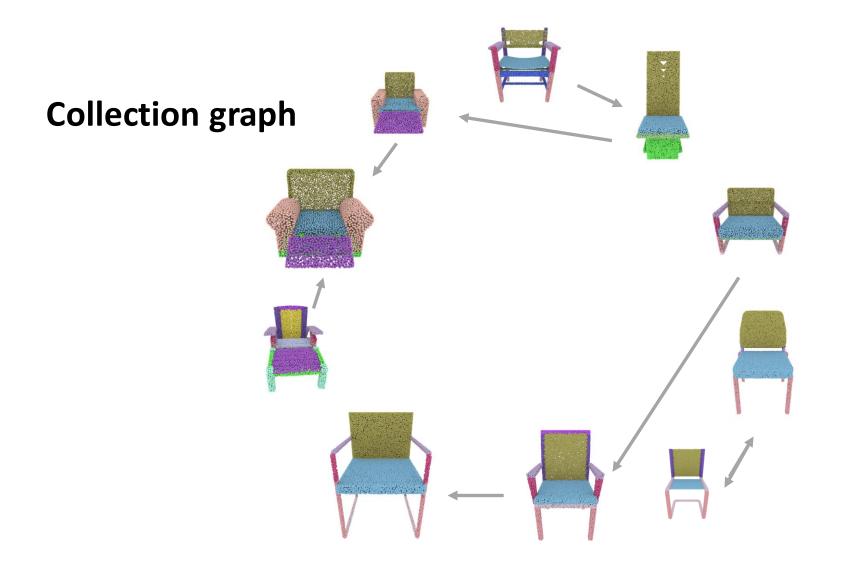


HRNet [Wang et al. 2021]

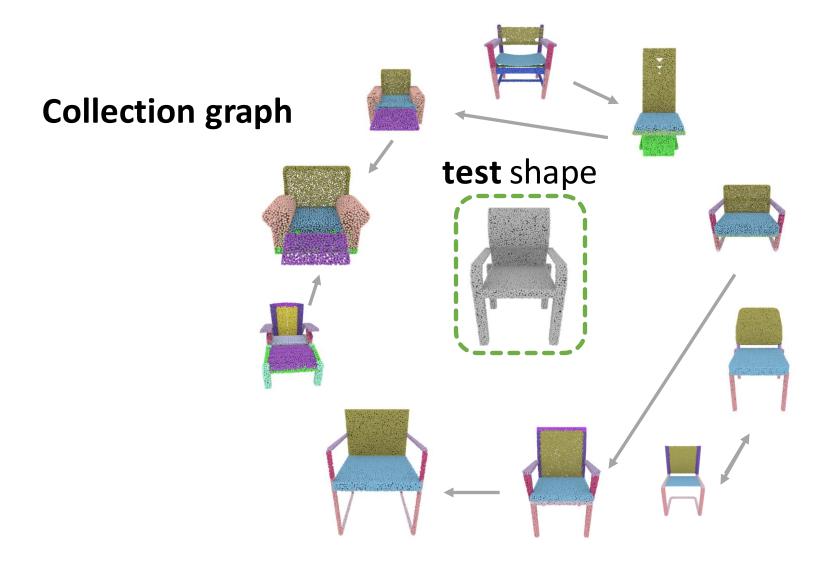




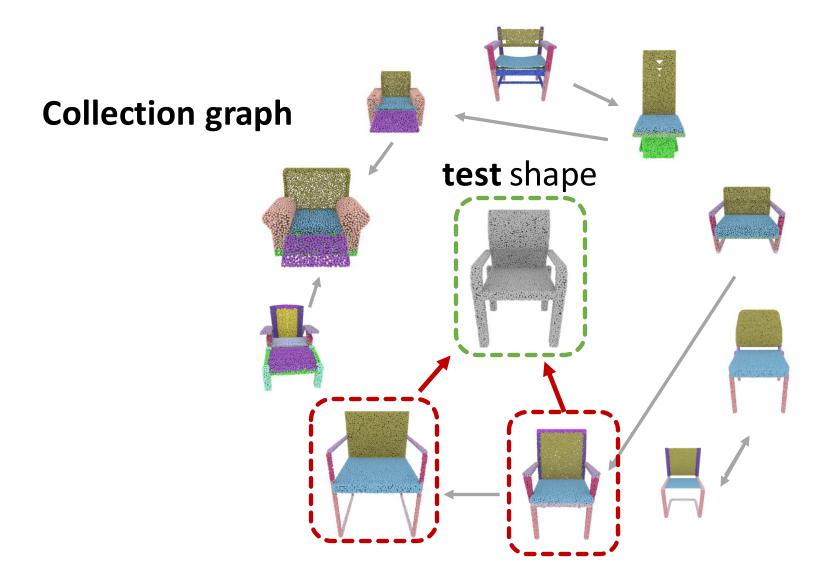




### Inference: Collection graph



### Inference: Collection graph



### Results

# Method Part IoU

Method	Part IoU
MinkHRNet	48.0

Method	Part IoU	
MinkHRNet	48.0	
MinkHRNetCSN-SSA	48.7	+0

Method	Part IoU
MinkHRNet	48.0
MinkHRNetCSN-SSA	48.7
MinkHRNetCSN-K1	49.9
MinkHRNetCSN-K2	49.7

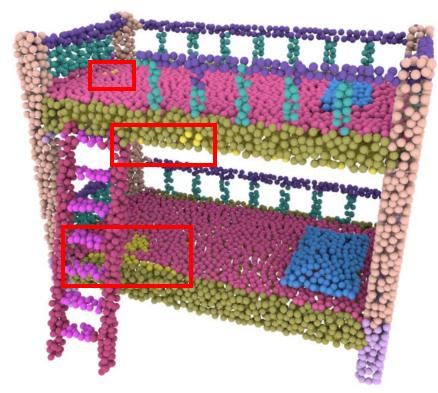
Method	Part IoU	
MinkHRNet	48.0	
MinkHRNetCSN-SSA	48.7	
MinkHRNetCSN-K1	49.9	+1.29
MinkHRNetCSN-K2	49.7	

### Ground truth



## Results: MinkowskiNet variants

#### MinkHRNet

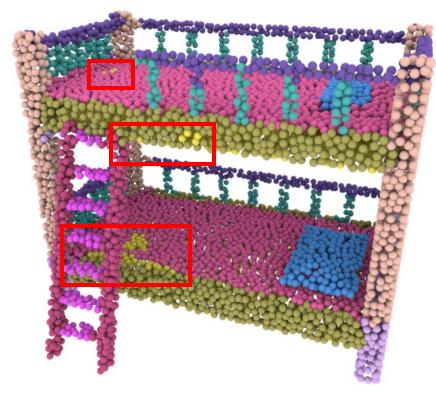


### Ground truth

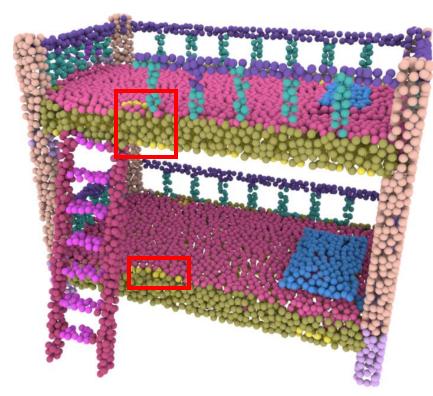
### Results: MinkowskiNet variants



### MinkHRNet



#### MinkHRNetCSN-SSA

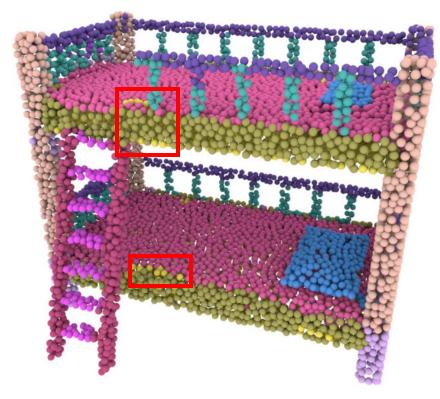


### Ground truth

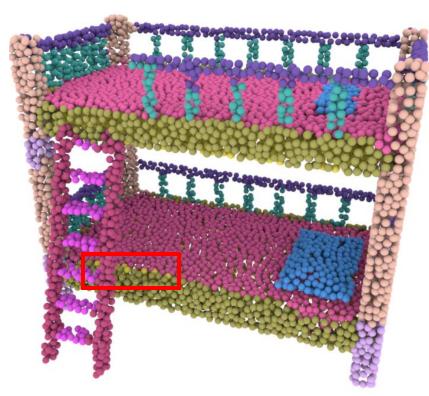


## Results: MinkowskiNet variants

MinkHRNetCSN-SSA



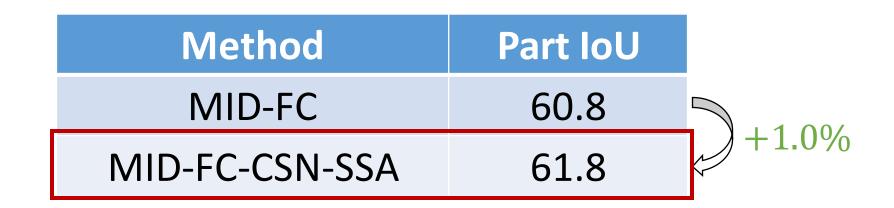
MinkHRNetCSN-K1



### **Results**: MID-FC variants

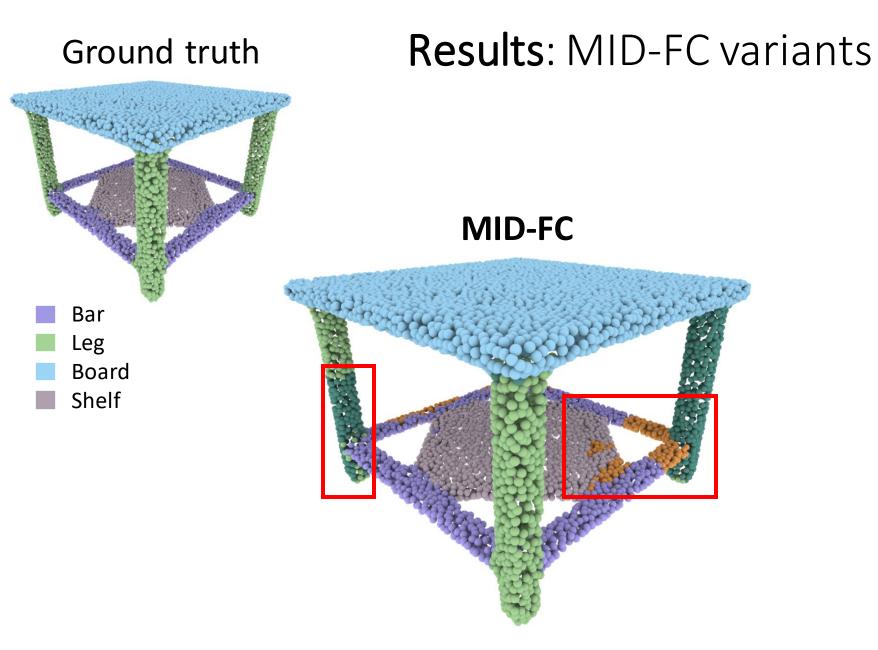
Method	Part IoU
MID-FC	60.8

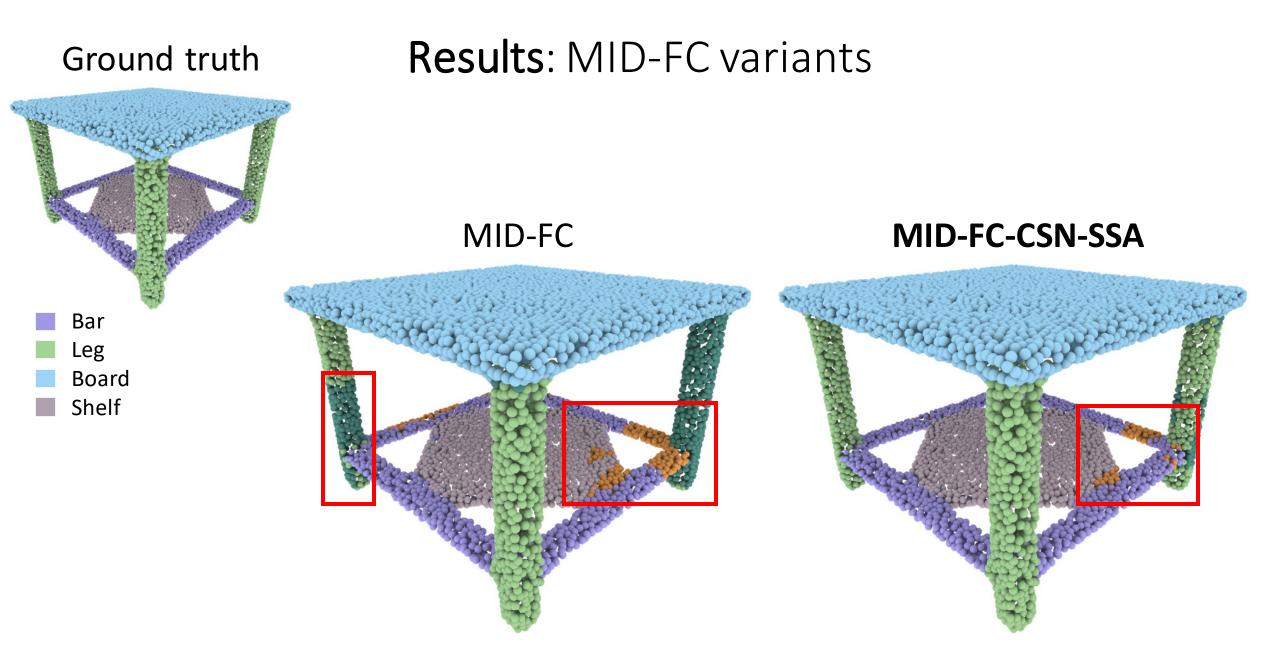
### **Results**: MID-FC variants

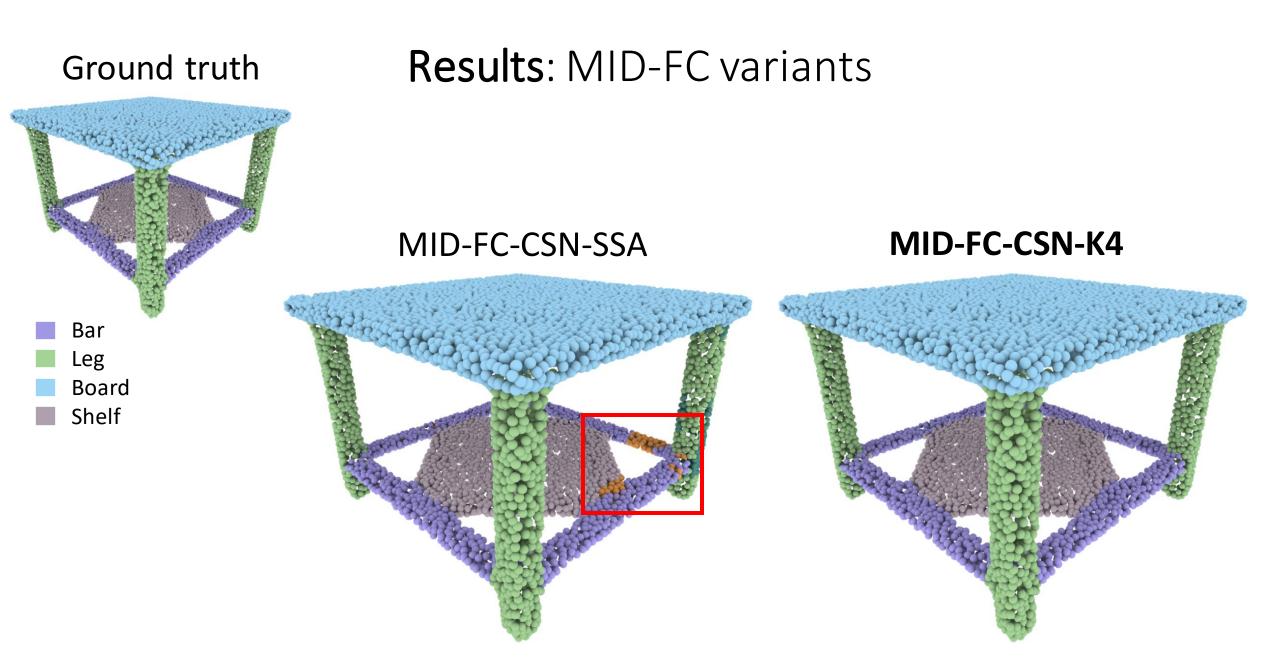


### **Results**: MID-FC variants

Method	Part IoU	
MID-FC	60.8	
MID-FC-CSN-SSA	61.8	
MID-FC-CSN-K1	61.9	
MID-FC-CSN-K2	61.9	+0.3%
MID-FC-CSN-K3	62.0	
MID-FC-CSN-K4	62.1	
MID-FC-CSN-K5	62.0	







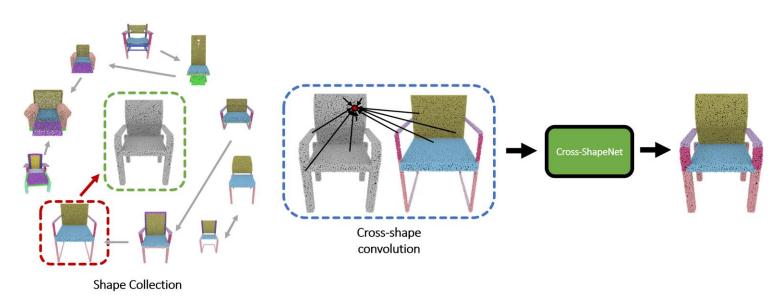
Method	Part IoU
ResGCN-28 (Li et al. 2023)	45.1
CloserLook3D (Liu et al. 2020)	53.8
MinkResUNet (Choy et al. 2019)	46.8
MinkHRNetCSN-K1 (ours)	49.9
MID-FC (Wang et al. 2021)	60.8
MID-FC-CSN-K4 (ours)	62.1

Method	Part IoU
ResGCN-28 (Li et al. 2023)	45.1
CloserLook3D (Liu et al. 2020)	53.8
MinkResUNet (Choy et al. 2019)	46.8
MinkHRNetCSN-K1 (ours)	49.9
MID-FC (Wang et al. 2021)	60.8
MID-FC-CSN-K4 (ours)	62.1

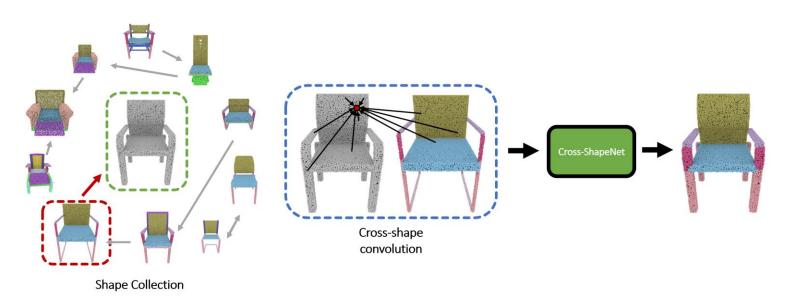
Method	Part IoU
ResGCN-28 (Li et al. 2023)	45.1
CloserLook3D (Liu et al. 2020)	53.8
MinkResUNet (Choy et al. 2019)	46.8
MinkHRNetCSN-K1 (ours)	49.9
MID-FC (Wang et al. 2021)	60.8
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Method	Part IoU
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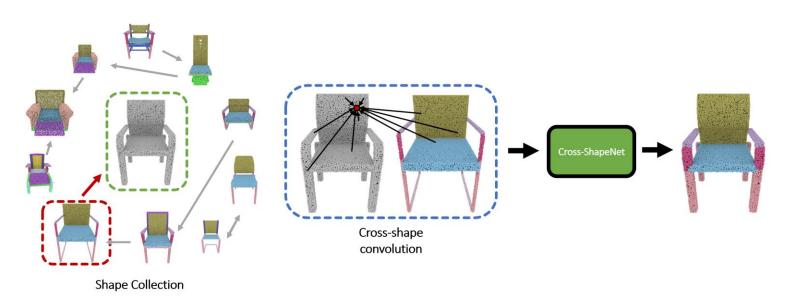
**SOTA performance on the PartNet dataset** 



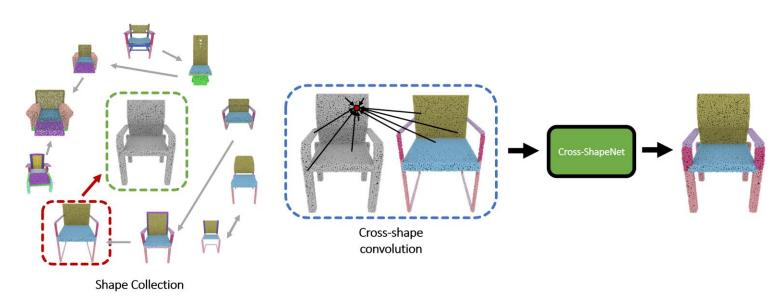
• Enable long range point feature interactions across shapes



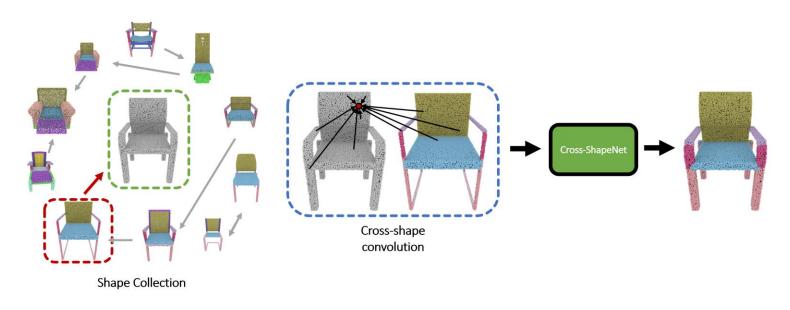
- Enable long range point feature interactions across shapes
- Introduce a **novel cross-shape attention** mechanism



- Enable long range point feature interactions across shapes
- Introduce a **novel cross-shape attention** mechanism
- Retrieve compatible shapes for cross-shape attention

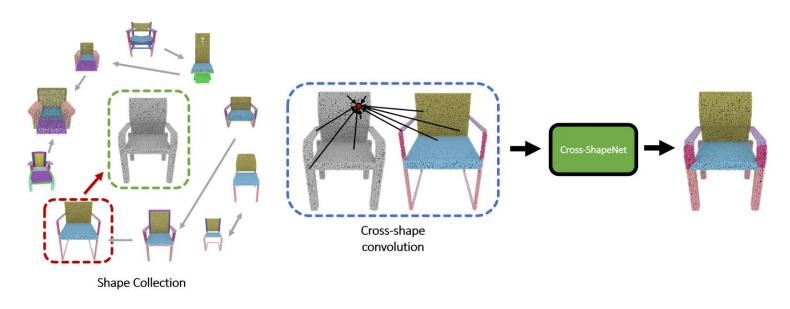


- Enable long range point feature interactions across shapes
- Introduce a **novel cross-shape attention** mechanism
- Retrieve compatible shapes for cross-shape attention
- SOTA performance on PartNet



#### Limitations:

• Increased computational cost due to shape retrieval



#### Limitations:

- Increased computational cost due to shape retrieval
- Currently no support for **multi-object scenes**

# Thank you!

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Our project web page: https://marios2019.github.io/CSN/

